

# ON THE POROSITY OF FREE BOUNDARIES IN DEGENERATE VARIATIONAL INEQUALITIES

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ABSTRACT. In this note we consider a certain degenerate variational problem with zero constraint. The exact growth of the solution near the free boundary is established. A consequence of this is that the free boundary is porous and therefore its Hausdorff dimension is less than  $N$  and hence it is of Lebesgue measure zero.

## 1. Preliminaries and the main result

In this paper we consider the obstacle problem for the nonhomogeneous  $p$ -Laplace equation ( $1 < p < \infty$ )

$$\operatorname{div}(|\nabla u(x)|^{p-2}\nabla u(x)) = f(x),$$

with zero obstacle. Given a bounded open subset  $\Omega$  of  $\mathbb{R}^N$ ,  $N \geq 2$ , and  $\theta$  in  $W^{1,p}(\Omega) \cap L^\infty(\Omega)$ , we define

$$\mathcal{K}_\theta = \{v \in W^{1,p}(\Omega) : v - \theta \in W_0^{1,p}(\Omega), v \geq 0 \text{ a.e in } \Omega\}.$$

A function  $u$  in  $\mathcal{K}_\theta$  is a *solution to the obstacle problem* if

$$(1.1) \quad \int_{\Omega} (|\nabla u|^{p-2}\nabla u \cdot (\nabla v - \nabla u) + f(x)(v - u)) dx \geq 0$$

whenever  $v \in \mathcal{K}_\theta$ . According to a result of Choe and Lewis [CL] (see also [MZ]), the solution  $u$  to (1.1) lies in  $W^{1,p}(\Omega) \cap C^{1,\alpha}(\Omega)$  for some  $\alpha \in (0, 1)$ , provided  $f \in L^q(\Omega)$  for some  $q > N$ . We will assume that  $f \in L^\infty(\Omega)$ .

The solution  $u$  to the obstacle problem satisfies

$$(1.2) \quad \operatorname{div}(|\nabla u|^{p-2}\nabla u) = f\chi_{\overline{\Omega}_+} - \mu,$$

weakly in  $\Omega$ , where

$$\Omega_+ = \{x \in \Omega : u(x) > 0\}$$

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and  $\mu$  is a nonnegative Radon measure with  $\text{supp}\mu \subset \partial\Omega_+$ .

Plugging in (1.1) a test function  $v = u + \eta$  with  $\eta \in C_0^\infty(\Omega)$ ,  $\eta \geq 0$ , we see that  $f - \text{div}(|\nabla u|^{p-2}\nabla u)$  is a nonnegative distribution, hence a Radon measure. Since  $u$  vanishes outside  $\bar{\Omega}_+$ , this measure coincides with  $f$  there. To complete the proof of (1.2) we observe that if  $\eta \in C_0^\infty(\Omega_+)$ , then  $u \geq \delta > 0$  in the support of  $\eta$ . Thus  $v = u \pm \varphi$  with

$$\varphi = \delta \frac{\eta}{\|\eta\|_\infty},$$

are competing functions in  $\mathcal{K}_\theta$ . We conclude that  $f - \text{div}(|\nabla u|^{p-2}\nabla u) = 0$  in  $\Omega_+$ , and (1.2) is established.

As an opposite to (1.2) we have the following lemma.

**Lemma 1.1.** *Suppose that  $u \in W^{1,p}(\Omega)$  is a nonnegative continuous function with*

$$\text{div}(|\nabla u|^{p-2}\nabla u) = g \quad \text{in } \Omega_+ = \{u > 0\},$$

where  $g$  is a signed Radon measure, living in  $\Omega_+$ . Then there is a nonnegative Radon measure  $\nu$ , supported on  $\partial\Omega_+$  such that

$$\text{div}(|\nabla u|^{p-2}\nabla u) = g + \nu \quad \text{in } \Omega.$$

*Proof.* Let  $\eta \in C_0^\infty(\Omega)$ ,  $\eta \geq 0$ . For  $\varepsilon > 0$  define

$$\eta_\varepsilon = \eta\chi_\varepsilon,$$

where

$$\chi_\varepsilon = \begin{cases} 1 & \text{if } u(x) \geq 2\varepsilon \\ \frac{u(x)}{\varepsilon} - 1 & \text{if } \varepsilon < u(x) < 2\varepsilon \\ 0 & \text{if } u(x) \leq \varepsilon \end{cases}.$$

Then

$$\begin{aligned} -\langle \eta_\varepsilon, g \rangle &= \int_{\Omega_+} |\nabla u|^{p-2}\nabla u \cdot \nabla \eta_\varepsilon \, dx \\ &= \int_{\Omega} (|\nabla u|^{p-2}\nabla u \cdot \nabla \eta)\chi_\varepsilon \, dx + \frac{1}{\varepsilon} \int_{\varepsilon < u < 2\varepsilon} |\nabla u|^p \eta \, dx \\ &\geq \int_{\Omega} (|\nabla u|^{p-2}\nabla u \cdot \nabla \eta)\chi_\varepsilon \, dx. \end{aligned}$$

Passing to the limit as  $\varepsilon \rightarrow 0$ , which is legitimate since  $0 \leq \eta_\varepsilon \leq \eta$  and

$$\int_{\Omega} |\nabla u|^{p-1} |\nabla \eta| \, dx < \infty,$$

we obtain

$$-\langle \eta, g \rangle \geq \int_{\Omega_+} |\nabla u|^{p-2}\nabla u \cdot \nabla \eta \, dx = \int_{\Omega} |\nabla u|^{p-2}\nabla u \cdot \nabla \eta \, dx.$$

We have used that  $\nabla u = 0$  a.e. on  $\Omega \setminus \Omega_+$ . The last inequality is equivalent to the statement of the lemma and the proof is completed.  $\square$

**Lemma 1.2.** *Suppose that  $u$  is a solution to the obstacle problem (1.1) in  $\mathcal{K}_\theta$  with  $f \in L^q(\Omega)$  for some  $q > N$ . Then  $u$  is continuous and*

$$(1.3) \quad \operatorname{div}(|\nabla u|^{p-2}\nabla u) = h$$

*weakly in  $\Omega$  with  $h \in L^q(\Omega)$  satisfying*

$$(1.4) \quad f\chi_{\Omega_+} \leq h \leq f\chi_{\bar{\Omega}_+} \quad \text{a.e. in } \Omega.$$

*If, in addition,  $f \geq 0$  a.e. in  $\Omega$  then*

$$(1.5) \quad 0 \leq u \leq \|\theta\|_{\infty, \Omega} \quad \text{in } \Omega.$$

*Proof.* As noted before  $u$  is even  $C^{1,\alpha}$  regular; see [CL], [MZ]. Let  $h$  be a distribution defined by (1.3). From (1.2) and Lemma 1.1 with  $g = f\chi_{\Omega_+}$  it follows that

$$(1.6) \quad h = f\chi_{\bar{\Omega}_+} - \mu = f\chi_{\Omega_+} + \nu$$

where both  $\mu$  and  $\nu$  are *nonnegative* Radon measures, supported on  $\partial\Omega_+$ . Further, (1.6) implies

$$\mu + \nu = f\chi_{\partial\Omega_+}.$$

In particular, since  $f \in L^q(\Omega)$ , it follows that  $\mu, \nu \in L^q(\Omega)$  and therefore also  $h \in L^q(\Omega)$ . Inequality (1.4) follows now from (1.6).

To prove (1.5), we set  $v = \min\{u, \|\theta\|_{\infty, \Omega}\} \in \mathcal{K}_\theta$  in (1.1), and use the assumption  $f \geq 0$  to obtain  $v = u$ . Hence (1.5) follows.

The lemma is proved.  $\square$

To formulate the main result of this paper, we recall that a set  $E$  in  $\mathbb{R}^N$  is called *porous* with *porosity constant*  $\delta$  if there is an  $r_0 > 0$  such that for each  $x \in E$  and  $0 < r < r_0$  there is a point  $y$  such that  $B_{\delta r}(y) \subset B_r(x) \setminus E$ . A porous set has Hausdorff dimension not exceeding  $N - C\delta^N$ , where  $C = C(N) > 0$  is some constant (see e.g. Martio and Vuorinen [MV]). Consequently a porous set has Lebesgue measure zero.

**Theorem 1.3.** *Let  $u$  be a solution to the obstacle problem (1.1) in  $\mathcal{K}_\theta$  with  $f$  satisfying*

$$(1.7) \quad 0 < \lambda_0 \leq f \leq \Lambda_0 \quad \text{a.e. in } \Omega.$$

*Then for every compact set  $K \subset \Omega$  the intersection  $\partial\Omega_+ \cap K$  is porous with porosity constant  $\delta = \delta(\|\theta\|_{\infty, \Omega}, \lambda_0, \Lambda_0, \operatorname{dist}(K, \partial\Omega), p, N) > 0$ .*

We prove this theorem in section 3.

## 2. On a class of functions in the unit ball

The proof of Theorem 1.3 is based on the study of the following class of functions. We say that a function  $u$  in  $W^{1,p}(B_1)$ , where  $B_1 = B_1(0)$  is the unit ball in  $\mathbb{R}^N$ , belongs to the class  $\mathcal{G} = \mathcal{G}(p)$  ( $1 < p < \infty$ ) if

$$(2.1) \quad \|\operatorname{div}(|\nabla u|^{p-2}\nabla u)\|_{\infty} \leq 1;$$

$$(2.2) \quad 0 \leq u \leq 1 \quad \text{a.e. in } B_1;$$

$$(2.3) \quad u(0) = 0.$$

Condition (2.1) is understood in the weak sense, i.e.  $\operatorname{div}(|\nabla u|^{p-2}\nabla u) = h$  weakly for  $h \in L^\infty(B_1)$  with  $\|h\|_{\infty} \leq 1$ . Condition (2.3) makes sense since (2.1) and (2.2) provide that  $u \in C^{1,\alpha}(B_1)$  for some  $\alpha \in (0, 1)$ ; (see e.g. [CL], [MZ]).

**Theorem 2.1.** *There is a positive constant  $K = K(p, N)$  such that for every  $u \in \mathcal{G}$ , there holds*

$$|u(x)| \leq K|x|^{p/(p-1)} \quad \forall x \in B_1.$$

For a given nonnegative bounded function  $u$ , set

$$S(r, u, z) = \sup_{x \in B_r(z)} u(x), \quad S(r, u) = S(r, u, 0)$$

and for  $u$  in  $\mathcal{G}$  define  $\mathbb{M}(u)$  to be the set of all nonnegative integers  $j$  such that the following doubling condition holds

$$(2.4) \quad 2^{p/(p-1)} S(2^{-j-1}, u) \geq S(2^{-j}, u).$$

**Lemma 2.2.** *There exists a constant  $K = K(p, N)$  such that*

$$S(2^{-j-1}, u) \leq K (2^{-j})^{p/(p-1)},$$

for all  $u \in \mathcal{G}$ , and  $j \in \mathbb{M}(u)$ .

*Proof.* We argue by contradiction. Thus we assume that for every  $k \in \mathbb{N}$ , there are  $u_k \in \mathcal{G}$  and  $j_k \in \mathbb{M}(u_k)$  such that

$$(2.5) \quad S(2^{-j_k-1}, u_k) \geq k (2^{-j_k})^{p/(p-1)}.$$

Define now

$$(2.6) \quad \tilde{u}_k(x) := \frac{u_k(2^{-j_k}x)}{S(2^{-j_k-1}, u_k)} \quad \text{in } B_1.$$

Then it follows from the definition of  $\mathbb{M}(u)$  and  $\mathcal{G}$  that

$$(2.7) \quad 0 \leq \tilde{u}_k \leq 2^{p/(p-1)} \quad (\text{by (2.1)})$$

$$(2.8) \quad \sup_{B_{(1/2)}} |\tilde{u}_k| = 1 \quad (\text{by (2.6)})$$

$$(2.9) \quad \tilde{u}_k(0) = 0 \quad (\text{by (2.3)})$$

Now we have by (2.1) and (2.5) that

$$(2.10) \quad \|\operatorname{div}(|\nabla \tilde{u}_k|^{p-2} \nabla \tilde{u}_k)\|_\infty \leq k^{1-p}.$$

Invoking Harnack inequalities and Hölder estimates of solutions (see e.g. [Se]) we infer that a subsequence of  $\tilde{u}_k$  converges locally uniformly in  $B_1$  to a function  $u$ . Moreover, the limit function  $u \not\equiv 0$ , by (2.8), and it satisfies by (2.9) and (2.10)

$$\operatorname{div}(|\nabla u|^{p-2} \nabla u) = 0, \quad u(0) = 0, \quad u \geq 0,$$

in  $B_1$ . This, however, contradicts the strict minimum principle (see [HKM, 7.12]) and the lemma follows.  $\square$

*Proof of Theorem 2.1.* We first claim that

$$(2.11) \quad S(2^{-j}, u) \leq K(2^{-j+1})^{p/(p-1)}$$

for all  $j \in \mathbb{N}$ , where  $K$  is the constant in Lemma 2.2. Without loss of generality we may assume that  $K \geq 1$ . Thus (2.11) holds for  $j = 0$ . Next, let (2.11) hold for some  $j \in \mathbb{N}$ . Then it holds also for  $j + 1$ . Indeed, if  $j \in \mathbb{M}(u)$  then this follows from Lemma 2.2. Otherwise, (2.4) fails and we obtain

$$S(2^{-j-1}, u) \leq 2^{-p/(p-1)} S(2^{-j}, u) \leq 2^{-p/(p-1)} K(2^{-j+1})^{p/(p-1)} = K(2^{-j})^{p/(p-1)}.$$

Thus (2.11) is established.

To complete the proof, let  $2^{-j-1} \leq r \leq 2^{-j}$ . Then by (2.11)

$$S(r, u) \leq S(2^{-j}, u) \leq K (2^{-j-1})^{p/(p-1)} \leq K r^{p/(p-1)},$$

and the theorem is proved.  $\square$

### 3. Proof of Theorem 1.3

The next lemma shows that Theorem 2.1 gives, in a sense, the exact growth of the solution to the obstacle problem (1.1) near the free boundary  $\partial\Omega_+$ . The lemma originates from the paper of Caffarelli [Ca].

**Lemma 3.1.** *Suppose that  $u \in W^{1,p}(\Omega)$  is a nonnegative continuous function satisfying*

$$\operatorname{div}(|\nabla u|^{p-2}\nabla u) = f$$

*weakly in  $\Omega_+ = \{u > 0\}$  with  $f$  as in (1.7). Then for every  $z \in \overline{\Omega}_+$  and  $r > 0$  with  $B_r(z) \subset \Omega$*

$$S(r, u, z) \geq C_0 r^{p/(p-1)} + u(z),$$

*where  $C_0 = (1 - 1/p)(\lambda_0/N)^{1/(p-1)}$ .*

*Proof.* First suppose that  $z \in \Omega_+$ , and for small  $\varepsilon > 0$  set

$$w_\varepsilon(x) = u(x) - u(z)(1 - \varepsilon), \quad v(x) = C_0|x - z|^{p/(p-1)}.$$

Then  $\operatorname{div}(|\nabla v|^{p-2}\nabla v) = \lambda_0$  and therefore

$$\operatorname{div}(|\nabla w_\varepsilon|^{p-2}\nabla w_\varepsilon) = \operatorname{div}(|\nabla u|^{p-2}\nabla u) \geq \operatorname{div}(|\nabla v|^{p-2}\nabla v)$$

in  $\Omega_+ \cap B_r(z)$ , and  $w_\varepsilon \leq v$  on  $\partial\Omega_+ \cap B_r(z)$ . If also  $w_\varepsilon \leq v$  on  $\partial B_r(z) \cap \Omega$ , then we may apply the comparison principle to obtain  $w_\varepsilon \leq v$  in  $B_r(z) \cap \Omega_+$ , which contradicts to the fact that  $w_\varepsilon(z) = \varepsilon u(z) > 0 = v(z)$ . Hence

$$\sup_{\partial B_r(z)} w_\varepsilon \geq \sup_{\partial B_r(z)} v = C_0 r^{p/(p-1)}.$$

Letting  $\varepsilon \rightarrow 0$ , we obtain the desired result, for all  $z \in \Omega_+$ , and by continuity for all  $z \in \overline{\Omega}_+$ . The proof is completed.  $\square$

*Proof of Theorem 1.3.* Without loss of generality we may assume that the compact  $K$  in Theorem 1.3 is the closed unit ball  $\overline{B}_1$ , and moreover that  $\overline{B}_2 \subset \Omega$ .

For  $x \in \Omega_+ \cap \overline{B}_1$  define

$$d(x) = \operatorname{dist}(x, \overline{B}_1 \setminus \Omega_+)$$

and take  $z_x \in \partial\Omega_+ \cap \overline{B}_1$  with  $|x - z_x| = d(x)$ . Let

$$\tilde{u}(y) = u(z_x + y) \quad \text{for } y \in B_1.$$

Then, using Lemma 1.2 and condition (1.7), we see that

$$\|\operatorname{div}(|\nabla \tilde{u}|^{p-2}\nabla \tilde{u})\|_\infty \leq \Lambda_0, \quad 0 \leq \tilde{u} \leq \|\theta\|_{\infty, \Omega}, \quad \tilde{u}(0) = 0.$$

Therefore if  $M = \max\{\Lambda_0^{1/(p-1)}, \|\theta\|_{\infty, \Omega}\}$ , then  $\tilde{u}/M$  is in  $\mathcal{G}$  and we infer by Theorem 2.1 that

$$(3.1) \quad u(x) = \tilde{u}(x - z_x) \leq MK|x - z_x|^{p/(p-1)} = MKd(x)^{p/(p-1)}.$$

Next, let  $z \in \partial\Omega_+ \cap \overline{B}_1$ . Then for  $0 < r < 1$ , according to Lemma 3.1, there exists  $x_z \in \partial B_r(z)$ , such that

$$u(x_z) \geq C_0 r^{p/(p-1)}.$$

Then by (3.1)

$$C_0 r^{p/(p-1)} \leq u(x_z) \leq MK d(x_z)^{p/(p-1)},$$

which implies that

$$d(x_z) \geq \delta r, \quad \delta = \left( \frac{C_0}{MK} \right)^{(p-1)/p},$$

or equivalently,

$$B_{\delta r}(x_z) \cap B_r(z) \subset \Omega_+.$$

Note that  $\delta \leq 1$ . Since  $x_z \in \partial B_r(z)$ , there is a ball

$$B_{(\delta/2)r}(y) \subset B_{\delta r}(x) \cap B_r(z) \subset B_r(z) \setminus \partial\Omega_+.$$

This shows that  $\partial\Omega_+ \cap \overline{B}_1$  is porous with the porosity constant  $\delta/2$ . The theorem is proved.  $\square$

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