

# COMPLEX SPHERICAL WAVES AND INVERSE PROBLEMS IN UNBOUNDED DOMAINS

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ABSTRACT. This work is motivated by the inverse conductivity problem of identifying an embedded object in an infinite slab. The novelty of our approach is that we use *complex spherical waves* rather than classical Calderón type functions. For Calderón type functions, they are growing exponentially on one side of a *hyperplane* and decaying exponentially on the other side. Without extra modifications, they are inadequate for treating inverse problems in unbounded domains such as the infinite slab. The obvious reason for this is that Calderón type functions are not integrable on hyperplanes. So they can not be used as measurements on infinite boundaries.

For complex spherical waves used here, they blow up faster than any given positive polynomial order on the inner side of the unit sphere and decay to zero faster than any given negative polynomial order on the outer side of the unit sphere. We shall construct these special solutions for the conductivity equation in the unbounded domain by a Carleman estimate. Using complex spherical waves, we can treat the inverse problem of determining the object in the infinite slab like the problem in the bounded domain. Most importantly, we can easily localize the boundary measurement, which is of great value in practice. On the other hand, since the probing fronts are spheres, it is possible to detect some concave parts of the object.

## 1. INTRODUCTION

Special solutions for elliptic equations or systems have played an important role in inverse problems since the pioneering work of Calderón [1]. In 1987, Sylvester and Uhlmann [13] introduced complex geometrical optics solutions to solve the inverse boundary value problem for the conductivity equation. Other type of special solutions, called oscillating-decaying solutions, were constructed for general elliptic systems in [10] and [12]. These oscillating-decaying solutions have been used in solving inverse problems, in particular in detecting inclusions and cavities [10].

In developing the theory for inverse boundary value problems with partial measurements, approximate complex geometrical optics solutions concentrated near hyperplanes and near hemispheres for the Schrödinger equation were given in [3] and [6], respectively. In [6], the construction was based on hyperbolic geometry and was applied in [4] to construct complex geometrical optics solutions for the Schrödinger equation where the real part of the phase function is a radial function, i.e., its level surfaces are spheres. These solutions are called *complex spherical waves* in [4]. An important feature of these solutions is that they decay exponentially on one side of the sphere and grow exponentially on the other side. The hyperbolic geometry approach does not seem to work for the Laplacian with first order perturbations, such as the Schrödinger equation with magnetic potential and the isotropic elasticity. Recently, using Carleman estimates, complex spherical waves were constructed for the Schrödinger equation in [8], for the Schrödinger equation with magnetic potential in [2], and for the isotropic elasticity in [14]. The Carleman estimate is a more flexible tool in treating lower order perturbations.

With these complex spherical waves at hand, one can study the inverse problem of reconstructing unknown inclusions or cavities embedded in a body with known background medium. For the conductivity equation, this problem was documented in [4]. There are several results, both theoretical and numerical, concerning the object identification problem by boundary measurements for the conductivity equation. We will not try to give a full account of these developments here. For detailed references, we refer to [4]. Here we want to point out that there are two striking advantages in using complex spherical waves for object identification problems. On one hand, one can avoid using a unique continuation procedure, more precisely, the Runge approximation, in the reconstruction. On the other hand, by the decaying property of complex spherical waves across the spherical front, the measurements can be easily localized.

The construction of complex spherical waves and the inverse problems studied in the literature cited above were restricted to bounded domains. However, there are many interesting inverse problems whose background domains are unbounded, for instance, identifying an object embedded in an infinite slab. In fact, our work here is motivated by this inverse problem. Ikehata in [5] studied the inverse conductivity problem in an infinite slab where the location of an inclusion is reconstructed by infinitely many boundary measurements. In [5], he used Calderón type harmonic functions, i.e.,  $e^{x \cdot (\omega + i\omega^\perp)}$  with  $\omega \in \mathbb{S}^{n-1}$ . These

functions are not integrable on hyperplanes. Therefore, they can not be the Dirichlet data of solutions with finite energy. To remedy this, he introduced Yarmukhamedov's Green function to construct a sequence of harmonic functions with finite energy that approximate the Calderón type function on a bounded part of the slab and are arbitrarily small on an unbounded part of the slab.

In this paper we use complex spherical waves rather than Calderón type functions for the inverse problem in the slab. The most obvious advantage is that we do not need Yarmukhamedov's Green function to "localize" complex spherical waves since we can make these solutions decay faster than any given polynomial order on infinite hyperplanes. Therefore, we can treat the problem in the infinite slab like that in the bounded domain. Furthermore, we can handle the inhomogeneous background medium without requiring the Runge approximation property. Also, since our probing fronts are spheres, we are able to determine some concave parts of the embedded object.

This paper is organized as follows. In Section 2, we discuss a Carleman estimate needed in our proof and its consequence. In Section 3, we construct complex spherical waves in the unbounded domain by means of the Carleman estimate. The investigation of the inverse problem in the infinite slab will be discussed in Section 4.

## 2. CARLEMAN ESTIMATE AND RELATED CONSEQUENCE

As in [2], [8], and [14], we construct complex spherical waves in the unbounded domain via a Carleman estimate. Let  $p \in \mathbb{R}^n$ ,  $n \geq 2$ , be a fixed point. Let  $B_\varepsilon(p)$  be the ball of radius  $\varepsilon > 0$  centered at  $p$ . Without loss of generality, we take  $p = 0$ . We denote  $U = \overline{B_\varepsilon(0)}^c$ . From [2] and [8], we see that  $\varphi(x) = \log|x|$  is a limiting Carleman weight for the semiclassical Laplacian  $-h^2\Delta$  in  $U$ . Namely, if  $a(x, \xi) = |\xi|^2 - |\varphi'_x|^2$  and  $b(x, \xi) = 2\varphi'_x \cdot \xi$ , then

$$\{a, b\}(x, \xi) = 0 \quad \text{when} \quad a(x, \xi) = b(x, \xi) = 0.$$

Here  $\{a, b\} = a'_\xi \cdot b'_x - a'_x \cdot b'_\xi$  is the Poisson bracket of  $a, b$ . With such  $\varphi$ , we have

$$e^{-\varphi/h} = |x|^{-1/h}.$$

So  $e^{-\varphi/h}$  becomes a polynomial weight. Carleman estimates with polynomial weights are well known in proving the strong unique continuation property for Schrödinger operators with singular potentials, see, for example, [7]. Since we will work in  $L^2$ -based spaces, it is enough to use a simpler  $L^2$  Carleman estimate given for instance in [11].

**Lemma 2.1.** [11, Lemma 2.1] *There exists a  $C > 0$  such that for any  $v \in C_c^\infty(\mathbb{R}^n \setminus \{0\})$  and for any  $\frac{1}{h} \in \{k + \frac{1}{2} : k \in \mathbb{N}\}$  with  $h \ll 1$ , we have that*

$$h^2 \int |x|^{-2/h} |v|^2 |x|^{-n} dx \leq C \int |x|^{-2/h+4} |h^2 \Delta v|^2 |x|^{-n} dx. \quad (2.1)$$

Here the constant  $C$  is independent of  $v$  and  $h$ .

Now we replace  $1/h$  by  $1/h - n - \delta$  such that

$$h \in S := \{(k + n + \delta + \frac{1}{2})^{-1} : k \in \mathbb{N}\},$$

where  $\delta > 0$ . Then (2.1) implies that for  $v \in C_c^\infty(U)$  and sufficiently small  $h \in S$  we have

$$h^2 \int |x|^{-2/h} |v|^2 |x|^{n+2\delta} dx \leq C \int |x|^{-2/h} |h^2 \Delta v|^2 |x|^{n+4+2\delta} dx \quad (2.2)$$

with possibly different constant  $C$ . Let  $q \in L_c^\infty(U)$  and  $P_h^* = |x|^{-1/h} h^2 (\Delta - \bar{q}) |x|^{1/h}$ . Then we get from (2.2) that

$$h \|v\|_{L_{\frac{n}{2}+\delta}^2(U)} \leq C \|P_h^* v\|_{L_{\frac{n}{2}+2+\delta}^2(U)} \quad (2.3)$$

for all  $v \in C_c^\infty(U)$  and small  $h \in S$ , where  $L_s^2(U)$  is the weighted  $L^2$  space with norm  $\|f\|_{L_s^2(U)} = \|\langle x \rangle^s f\|_{L^2(\Omega)}$ , where  $\langle x \rangle = \sqrt{1 + |x|^2}$ . Combining (2.3) and the Hahn-Banach theorem, we prove the following existence theorem.

**Proposition 2.2.** *For any  $f \in L_{-\frac{n}{2}-\delta}^2(U)$ , there exists  $w \in L_{-\frac{n}{2}-2-\delta}^2(U)$  such that*

$$P_h w := |x|^{1/h} h^2 (\Delta - q) (|x|^{-1/h} w) = f \quad \text{in } U$$

and

$$h \|w\|_{L_{-\frac{n}{2}-2-\delta}^2(U)} \leq C \|f\|_{L_{-\frac{n}{2}-\delta}^2(U)}.$$

**Proof.** Let us denote  $\mathcal{D} = C_c^\infty(U)$ . For  $f \in L_{-\frac{n}{2}-\delta}^2(U)$ , we define a linear functional  $\ell$  on the linear subspace  $L = P_h^* \mathcal{D}$  of  $L_{\frac{n}{2}+2+\delta}^2(U)$  as follows:

$$\ell(P_h^* v) = \langle v, f \rangle_{L^2(U)}.$$

Using (2.3), we obtain

$$|\ell(P_h^* v)| \leq \|v\|_{L_{\frac{n}{2}+\delta}^2(U)} \|f\|_{L_{-\frac{n}{2}-\delta}^2(U)} \leq \frac{C}{h} \|P_h^* v\|_{L_{\frac{n}{2}+2+\delta}^2(U)} \|f\|_{L_{-\frac{n}{2}-\delta}^2(U)}.$$

So by the Hahn-Banach theorem,  $\ell$  can be extended to a linear functional on  $L^2_{-\frac{n}{2}+2+\delta}(U)$  with the same norm. Therefore, there exists a  $w \in L^2_{-\frac{n}{2}-2-\delta}(U)$  such that for  $v \in C_c^\infty(\Omega)$

$$\langle P_h^* v, w \rangle_{L^2(U)} = \langle v, f \rangle_{L^2(U)}$$

and

$$h \|w\|_{L^2_{-\frac{n}{2}-2-\delta}(U)} \leq C \|f\|_{L^2_{-\frac{n}{2}-\delta}(U)}.$$

The proof of proposition is now complete.  $\square$

### 3. COMPLEX SPHERICAL WAVES IN UNBOUNDED DOMAINS

In this section we will construct complex spherical waves for the conductivity equation in the unbounded domain  $\Omega = \{x \in \mathbb{R}^n : x_n < d\}$  where  $d < 0$ . It is clear that  $\bar{\Omega} \subset U (= \overline{B_\varepsilon(0)^c})$  for some  $\varepsilon > 0$ . Let  $0 < \gamma(x) \in C^2(\bar{\Omega})$  and  $\gamma = 1$  in  $B_R(0)^c \cap \Omega$  for some  $R > 0$ . We look for a function  $v = |x|^{-1/h} \tilde{v}$  with  $h \in S$  satisfying

$$Lv := \nabla \cdot (\gamma \nabla v) = 0 \quad \text{in } \Omega. \quad (3.1)$$

Using the Liouville transform  $w = \sqrt{\gamma} v$ , we know that if  $w$  solves

$$Pw := -\Delta w + qw = 0$$

with  $q = \Delta \sqrt{\gamma} / \sqrt{\gamma}$  then  $v$  solves (3.1). Here we note that  $q \in L_c^\infty(\Omega)$ . We want to point out that by checking the proofs in [4], complex spherical waves constructed there can be extended to the unbounded domain  $\Omega$ . In this work we take a different route using the Carleman estimate which can be adapted to other equations more easily.

As in [2] and [8], we want to construct solutions to  $Pw = 0$  in  $\Omega$  which have the form

$$w = e^{-\rho(x)/h} (a + r),$$

where  $\rho = \varphi + i\psi$  and  $\varphi, \psi$  are given by

$$\begin{aligned} \varphi(x) &= \log |x|, \\ \psi(x) &= \text{dist}_{\mathbb{S}^{n-1}}\left(\frac{x}{|x|}, e_1\right). \end{aligned}$$

Our first goal is to see what  $a$  will look like. To this end, we change coordinates and write  $x = (x_1, x')$  where  $x' = r\theta$  with  $r > 0$  and  $\theta \in \mathbb{S}^{n-2}$ . We take  $z = x_1 + ir$  to be a complex variable, and let  $\Psi : x \mapsto (z, \theta)$  be the corresponding change of coordinates in  $\Omega$ . If  $f$  is a function in  $\Omega$  we write  $\tilde{f} = f \circ \Psi^{-1}$ . Thus we can see that

$$\begin{aligned} \tilde{\rho} &= \log z, \\ (\nabla \rho)^\sim &= \frac{1}{z} (e_1 + ie_r) \quad \text{with } e_r = (0, \theta), \end{aligned}$$

and

$$(\Delta\rho)^\sim = -\frac{2(n-2)}{z(z-\bar{z})}.$$

Also,  $\nabla\rho \cdot \nabla$  becomes  $(2/z)\partial_{\bar{z}}$  in the new coordinates.

Writing  $h^2P = (-ih\nabla)^2 + h^2q$ , we have

$$\begin{aligned} e^{\rho/h}h^2Pe^{-\rho/h} &= (-ih\nabla + i\nabla\rho)^2 + h^2q \\ &= -(\nabla\rho)^2 + h(2\nabla\rho \cdot \nabla + \Delta\rho) + h^2P \\ &= h(2\nabla\rho \cdot \nabla + \Delta\rho) + h^2P. \end{aligned} \quad (3.2)$$

Here,  $\varphi$  and  $\psi$  were chosen so that  $(\nabla\rho)^2 = 0$ . To get  $P(e^{-\rho/h}(a+r)) = 0$ , we choose  $a$  and  $r$  to satisfy in  $\Omega$

$$(\nabla\rho \cdot \nabla + \frac{1}{2}\Delta\rho)a = 0 \quad (3.3)$$

and

$$e^{\rho/h}h^2Pe^{-\rho/h}r = -h^2Pa. \quad (3.4)$$

The first equation (3.3) is a transport equation for  $a$ . Writing  $a = \tilde{a} \circ \Psi$ , this reduces to

$$(\partial_{\bar{z}} - \frac{n-2}{2(z-\bar{z})})\tilde{a} = 0 \quad \text{in } \Psi(\Omega).$$

It is easy to see that the general solution is given by

$$\tilde{a} = (z-\bar{z})^{\frac{2-n}{2}}\tilde{g}$$

for any  $\tilde{g}(z, \theta)$  satisfying  $\partial_{\bar{z}}\tilde{g} = 0$ .

Taking  $\tilde{g} = 1$  and going back to the  $x$  coordinates, we obtain

$$a(x) = (2i|x'|)^{\frac{2-n}{2}}, \quad x \in \Omega. \quad (3.5)$$

In (3.4), the right hand side becomes

$$-h^2Pa = (2i)^{\frac{2-n}{2}}h^2\left(\frac{1}{4}(n-2)(4-n)|x'|^{-\frac{2-n}{2}} - q|x'|^{\frac{2-n}{2}}\right).$$

This decays in  $x'$  but is constant in  $x_1$ , so  $Pa \in L_s^2(\Omega)$  for  $s < -n/2$ .

We now rewrite (3.4) as

$$-|x|^{1/h}h^2P(|x|^{-1/h}e^{-i\psi/h}r) = e^{-i\psi/h}h^2Pa.$$

Since  $e^{-i\psi/h}h^2Pa \in L_s^2(\Omega)$  with  $s = -n/2 - \delta$  for some  $\delta > 0$ , we deduce from Proposition 2.2 that there exists  $r$  solving (3.4) and satisfying

$$\|r\|_{L_{-\frac{n}{2}-2-\delta}^2(\Omega)} \leq Ch. \quad (3.6)$$

Therefore, we have constructed the special solution  $w$  of  $-\Delta w + qw = 0$  in  $\Omega$  having the form

$$w = e^{-(\varphi+i\psi)/h}(a+r) = |x|^{-1/h}e^{-i\psi/h}(a+r)$$

with  $a$  given by (3.5) and  $r$  satisfying (3.6). In particular, we can see that  $w \in L^2(\Omega)$  for all sufficiently small  $h$ . Furthermore, since  $\Delta w = qw \in L^2(\Omega)$ , we can use a cut-off technique and the elliptic estimate to show that

$$w \in H^2(\tilde{\Omega}),$$

where  $\tilde{\Omega} = \{x \in \mathbb{R}^n : x_n < \tilde{d}\}$  for any  $\tilde{d} < d$ . In other words, the trace of  $w$  on any hyperplane  $H_b := \{x_n = b\}$  with  $b < \tilde{d}$  is well-defined and

$$\partial_{x_n} w|_{H_b} \in H^{1/2}.$$

This property is an important difference between complex spherical waves and Calderón type solutions.

In order to apply complex spherical waves to the inverse problem, we need to estimate the  $H^1$  norm of  $r$  on any fixed open subset of  $\Omega$ . Let  $\Omega_1$  and  $\Omega_2$  be two open bounded subsets of  $\Omega$  such that  $\overline{\Omega_1} \subset \Omega_2$  and  $\overline{\Omega_2} \subset \Omega$ . From (3.2) we see that

$$e^{\rho/h} h^2 P e^{-\rho/h} = -h^2 \Delta + h(2\nabla \rho \cdot \nabla + \Delta \rho) + h^2 q.$$

Therefore,  $e^{\rho/h} h^2 P e^{-\rho/h}$  is elliptic as a semiclassical operator. Furthermore, we have

$$\|e^{\rho/h} h^2 P e^{-\rho/h} r\|_{L^2(\Omega_2)} = \|h^2 P a\|_{L^2(\Omega_2)} \leq Ch^2$$

and

$$\|r\|_{L^2(\Omega_2)} \leq Ch.$$

Hence, by the semiclassical version of elliptic estimate [9, Lemma 2.6], we obtain that

$$\sum_{|\alpha| \leq 2} \|h^\alpha \partial^\alpha r\|_{L^2(\Omega_1)} \leq Ch,$$

in particular,

$$\|r\|_{L^2(\Omega_1)} + h \|\nabla r\|_{L^2(\Omega_1)} \leq Ch. \quad (3.7)$$

Finally, let  $p$  be any point such that  $\text{dist}(p, \Omega) > 0$ , then complex spherical waves for (3.1) in  $\Omega$  are given by

$$v = v(x, h) = \gamma^{-1/2} |x - p|^{-1/h} e^{-i\psi/h} (a + r)$$

for  $h \in S$  small, where  $\psi = \text{dist}_{\mathbb{S}^{n-1}}(\frac{x-p}{|x-p|}, e_1)$ ,  $a(x) = (2i|x' - p'|)^{\frac{2-n}{2}}$  and  $r$  satisfies (3.6) and (3.7). Note that for all  $x \in \Omega$  we have  $x' - p' = (x_2 - p_2, \dots, x_n - p_n) \neq 0$  since  $p_n > x_n$ .

## 4. INVERSE PROBLEM IN A SLAB

In this section we shall apply the special solutions we constructed above to the inverse problem in an infinite slab. We study the reconstruction of an embedded cavity here. The same method works for the inclusion case and so does the method in [4] or [14]. We leave this generalization to the interested reader. Let  $\Omega = \{x \in \mathbb{R}^n : d_1 < x_n < d_2, d_1 < d_2\}$ . Assume that  $D$  is a domain with  $C^2$  boundary in  $\Omega$  so that  $\bar{D} \subset \Omega$  and  $\Omega \setminus \bar{D}$  is connected. Let  $u(x)$  be the unique solution of finite energy to

$$\begin{cases} L_\gamma u = 0 & \text{in } \Omega \setminus \bar{D}, \\ \gamma \frac{\partial u}{\partial \nu} = 0 & \text{on } \partial D, \\ u = f \in H^{1/2} & \text{on } \partial\Omega, \end{cases} \quad (4.1)$$

where the conductivity parameter  $\gamma(x)$  satisfies the assumptions described in the previous section. The well-posedness of (4.1) can be proved by the standard Lax-Milgram theorem with a Poincaré-type inequality in the infinite slab: there exists  $C > 0$  independent of  $u$  such that

$$\int_{\Omega \setminus \bar{D}} |u|^2 dx \leq C \int_{\Omega \setminus \bar{D}} |\nabla u|^2 dx \quad (4.2)$$

for all  $u \in H^1(\Omega \setminus \bar{D})$  with  $u = 0$  on  $x_n = d_1$  and  $d_2$ . One possible way to prove (4.2) is to divide  $\Omega = Z \cup (\Omega \setminus Z)$ , where  $Z$  is a cylindrical domain of the form  $Z = B \times (d_1, d_2)$ ,  $B$  is a ball in  $\mathbb{R}^{n-1}$ , and  $\bar{D} \subset Z$ . Then (4.2) is a consequence of

$$\int_Z |v|^2 dx \leq C \int_Z |\nabla v|^2 dx \quad (4.3)$$

for all  $v \in H^1(Z)$  with  $v = 0$  on  $\partial Z \cap \{x_n = d_1, d_2\}$  and

$$\int_{\Omega \setminus \bar{Z}} |w|^2 dx \leq C \int_{\Omega \setminus \bar{Z}} |\nabla w|^2 dx \quad (4.4)$$

for all  $w \in H^1(\Omega \setminus \bar{Z})$  with  $w = 0$  on  $\partial(\Omega \setminus \bar{Z}) \cap \{x_n = d_1, d_2\}$ . Now (4.3) can be proved by a contradiction argument and (4.4) can be established by the usual integration technique. For brevity, we left the details to the reader.

The inverse problem here is to identify  $D$  from the Dirichlet-to-Neumann map  $\Lambda_D : H^{1/2}(\partial\Omega) \mapsto H^{-1/2}(\partial\Omega)$

$$\Lambda_D : f \mapsto \gamma \frac{\partial u}{\partial \nu} \Big|_{\partial\Omega}.$$

In the weak formulation, the Dirichlet-to-Neumann map is defined by

$$\langle \Lambda_D f, g \rangle = \int_{\Omega \setminus \bar{D}} \gamma \nabla u \cdot \nabla v dx,$$

where  $v \in H^1(\Omega \setminus \bar{D})$  with  $g = v|_{\partial\Omega}$ . We are interested in the reconstruction problem in this work.

Let  $\hat{\Omega} = \{x \in \mathbb{R}^3 : x_n < \hat{d}\}$  with  $d_2 < \hat{d}$  and  $t > 0$ . Pick any point  $p$  so that  $\text{dist}(p, \hat{\Omega}) > 0$ . We now denote complex spherical waves of  $L_\gamma v = 0$  in  $\hat{\Omega}$  by

$$v_t(x, h) = t^{1/h} \gamma^{-1/2} |x-p|^{-1/h} e^{-i\psi/h} (a+r) = \gamma^{-1/2} \left( \frac{t}{|x-p|} \right)^{1/h} e^{-i\psi/h} (a+r).$$

Let us define the energy gap functional

$$E_t(h) := \langle (\Lambda_0 - \Lambda_D) \bar{v}_t(x, h), v_t(x, h) \rangle = \int_{\partial\Omega} (\Lambda_0 - \Lambda_D) \bar{v}_t(x, h) \cdot v_t(x, h) ds,$$

where  $\Lambda_0$  is the Dirichlet-to-Neumann map for  $L_\gamma$  with  $D = \emptyset$ . Note that  $E_t(h)$  is well-defined for any  $t > 0$  even when  $\partial\Omega$  is unbounded. To understand how we reconstruct  $D$ , we first observe that  $E_t(h)$  can be estimated by

$$\frac{1}{C} \int_D |\nabla v_t(x, h)|^2 dx \leq E_t(h) \leq C \int_D (|\nabla v_t(x, h)|^2 + |v_t(x, h)|^2) dx \quad (4.5)$$

for some constant  $C > 0$ .

**Proof of (4.5).** Let  $u$  be the solution of (4.1) with  $f = v_t$ . We observe that

$$\int_{\Omega \setminus \bar{D}} \gamma \nabla u \cdot \nabla (\bar{u} - \bar{v}_t) dx = 0. \quad (4.6)$$

Using the definition of the Dirichlet-to-Neumann map and (4.6), we can compute

$$\begin{aligned}
& \langle (\Lambda_0 - \Lambda_D)\bar{v}_t, v_t \rangle \\
&= \int_{\partial\Omega} \gamma \frac{\partial \bar{v}_t}{\partial \nu} v_t ds - \int_{\partial\Omega} \gamma \frac{\partial \bar{u}}{\partial \nu} v_t ds \\
&= \int_{\Omega} \gamma \nabla \bar{v}_t \cdot \nabla v_t dx - \int_{\Omega \setminus \bar{D}} \gamma \nabla \bar{u} \cdot \nabla v_t dx \\
&= \int_{\Omega \setminus \bar{D}} \gamma \nabla \bar{v}_t \cdot \nabla v_t dx - \int_{\Omega \setminus \bar{D}} \gamma \nabla \bar{u} \cdot \nabla v_t dx + \int_{\Omega \setminus \bar{D}} \gamma \nabla u \cdot \nabla (\bar{u} - \bar{v}_t) dx \\
&\quad + \int_D \gamma |\nabla v_t|^2 dx \\
&= \int_D \gamma |\nabla v_t|^2 dx + \int_{\Omega \setminus \bar{D}} \gamma \nabla (u - v_t) \cdot \nabla (\bar{u} - \bar{v}_t) dx. \tag{4.7}
\end{aligned}$$

The formula (4.7) immediately implies the first inequality of (4.5).

To obtain the second inequality of (4.5), we need to estimate the last term in (4.7). Denote  $w = u - v_t$ . By the construction, we have that

$$\begin{cases} L_\gamma w = 0 & \text{in } \Omega \setminus \bar{D}, \\ \gamma \frac{\partial w}{\partial \nu} = -\gamma \frac{\partial v_t}{\partial \nu} & \text{on } \partial D, \\ w = 0 & \text{on } \partial\Omega. \end{cases}$$

It follows from the elliptic regularity theorem that

$$\|w\|_{H^1(\Omega \setminus \bar{D})} \leq C \left\| \gamma \frac{\partial v_t}{\partial \nu} \right\|_{H^{-1/2}(\partial D)}. \tag{4.8}$$

On the other hand, we know that  $L_\gamma v_t = 0$  in  $D$  and therefore,

$$\left\| \gamma \frac{\partial v_t}{\partial \nu} \right\|_{H^{-1/2}(\partial D)} \leq C \|v_t\|_{H^1(D)}. \tag{4.9}$$

Putting together (4.8) and (4.9) leads to

$$\|w\|_{H^1(\Omega \setminus \bar{D})} \leq C \|v_t\|_{H^1(D)}$$

and the second estimate in (4.5).  $\square$

Now we will use (4.5) to study the behaviors of  $E_t(h)$  as  $h \rightarrow 0$  and  $h \in S$  for different  $t$ 's.

**Theorem 4.1.** *Let  $\text{dist}(D, p) =: d_0 > 0$ . For  $t > 0$  and sufficiently small  $h \in S$ , we have that*

- (i). *If  $d_0 > t$ , then  $E_t(h) \leq C\alpha^{1/h}$  for some  $\alpha < 1$ ;*
- (ii). *If  $d_0 < t$ , then  $E_t(h) \geq C\beta^{1/h}$  for some  $\beta > 1$ ;*

(iii). If  $\overline{D} \cap \overline{B_t(p)} = \{y\}$ , then  $C^{-1}h^{n-2} \leq E_t(h) \leq Ch^{-1}$  for some  $C > 0$ .

**Proof.** (i). If  $\text{dist}(D, p) = d_0 > t$  then

$$\frac{t}{|x-p|} < 1 \quad \forall x \in \overline{D}.$$

Combining the second inequality of (4.5) and the behavior of  $v_t(x, h)$ , we immediately prove this statement.

(ii). We first pick a small ball  $B_\delta \subset\subset B_t(p) \cap D$ . Using (3.7), the leading term of  $\nabla v_t(x, h)$  is

$$-\frac{1}{h} \left( \frac{t}{|x-p|} \right)^{1/h} e^{-i\psi/h} \gamma^{-1/2} \nabla (\log |x-p| + i\psi) a. \quad (4.10)$$

We notice that  $\gamma^{-1/2} \nabla (\log |x-p| + i\psi) a \neq 0$  for all  $x \in B_\delta$ . So this statement follows from the first inequality of (4.5) and the fact

$$\frac{t}{|x-p|} > 1 \quad \forall x \in B_\delta.$$

(iii). Pick a small cone with vertex at  $y$ , say  $\Gamma$ , so that there exists an  $\epsilon > 0$  satisfying

$$\Gamma \cap \{0 < |x-y| < \epsilon\} \subset D.$$

It is not restrictive to take  $y = 0$  and  $p = (0, \dots, 0, t)$  for  $t > 0$ . Now we observe that if  $z \in \Gamma$  and  $|z-y| = |z| = s < \epsilon$  then

$$|z-p| \leq s+t,$$

that is

$$\frac{t}{|z-p|} \geq \frac{t}{s+t}.$$

Hence, from the first inequality of (4.5) and (4.10), for  $h \ll 1$  we have that

$$\begin{aligned} E_t(h) &\geq \frac{C}{h^2} \int_0^\epsilon \left( \frac{t}{s+t} \right)^{2/h} s^{n-1} ds \\ &\geq \frac{C}{h^2} \sum_{k=1}^n \frac{h}{2-kh} \\ &\geq Ch^{n-2}. \end{aligned}$$

On the other hand, we can choose a cone  $\tilde{\Gamma}$  with vertex at  $p$  such that  $\overline{D} \subset \tilde{\Gamma} \cap \{t \leq |x-p| < t+\eta\}$  for  $\eta > 0$ . Thus, by the second

inequality of (4.5) and (4.10), we can estimate

$$\begin{aligned} E_t(h) &\leq C(t+\eta)^{n-1} \frac{1}{h^2} \int_t^{t+\eta} \left(\frac{t}{s}\right)^{2/h} ds \\ &\leq Ch^{-1}. \end{aligned}$$

□

The distinct behavior of  $E_t(h)$  immediately allows us to detect the boundary of the cavity. However, Theorem 4.1 is unpractical since we need to take the measurements on the whole unbounded boundary. Fortunately, taking advantage of the decaying property of complex spherical waves, we are able to localize the measurement near the part where complex spherical waves are not decaying. To be precise, let  $\phi_{\delta,t}(x) \in C_0^\infty(\mathbb{R}^n)$  satisfy

$$\phi_{\delta,t}(x) = \begin{cases} 1 & \text{on } B_{t+\delta/2}(p) \\ 0 & \text{on } \mathbb{R}^n \setminus \overline{B_{t+\delta}(p)} \end{cases}$$

where  $\delta > 0$  is sufficiently small. Now we are going to use the measurement  $f_{\delta,t}(x, h) = \phi_{\delta,t} v_t(x, h)|_{\partial\Omega}$ . Clearly, the measurement  $f_{\delta,t}$  is localized on  $B_{t+\delta}(p) \cap \partial\Omega$ . In fact, if  $\delta$  is sufficiently small,  $f_{\delta,t}$  is localized on only one part of  $\partial\Omega$ , depending on whether  $p$  lies above or below  $\Omega$ . Let us define

$$E_{\delta,t}(h) = \langle (\Lambda_0 - \Lambda_D) \bar{f}_{\delta,t}, f_{\delta,t} \rangle.$$

**Theorem 4.2.** *The statements of Theorem 4.1 are valid for  $E_{\delta,t}(h)$ .*

**Proof.** The main idea is to prove that the error caused by the remaining part of the measurement  $g_{\delta,t} := (1 - \phi_{\delta,t})v_t(x, h)|_{\partial\Omega}$  is as small as any given polynomial order. Let  $w_{\delta,t}(x, h)$  be the unique solution of

$$L_\gamma w = 0 \quad \text{in } \Omega$$

with boundary value  $g_{\delta,t}$ . We now want to compare  $w_{\delta,t}$  with  $(1 - \phi_{\delta,t})v_t$ . To this end, we first observe that

$$\begin{cases} L_\gamma((1 - \phi_{\delta,t})v_t - w_{\delta,t}) = L_\gamma((1 - \phi_{\delta,t})v_t) & \text{in } \Omega, \\ (1 - \phi_{\delta,t})v_t - w_{\delta,t} = 0 & \text{on } \partial\Omega. \end{cases}$$

Notice that

$$L_\gamma((1 - \phi_{\delta,t})v_t) = (1 - \phi_{\delta,t})L_\gamma v_t + [L_\gamma, (1 - \phi_{\delta,t})]v_t = [L_\gamma, (1 - \phi_{\delta,t})]v_t.$$

So we see that

$$\text{supp } (L_\gamma((1 - \phi_{\delta,t})v_t)) \subset \bar{\Omega} \cap \{t + \delta/2 \leq |x - p| \leq t + \delta\}$$

and therefore

$$\|L_\gamma((1 - \phi_{\delta,t})v_t)\|_{L^2(\Omega)} \leq C\alpha_1^{1/h}$$

for some  $0 < \alpha_1 < 1$ . Consequently, we have that

$$\|(1 - \phi_{\delta,t})v_t - w_{\delta,t}\|_{H^1(\Omega)} \leq C\alpha_1^{1/h},$$

in particular,

$$\|(1 - \phi_{\delta,t})v_t - w_{\delta,t}\|_{H^1(D)} \leq C\alpha_1^{1/h}. \quad (4.11)$$

Using (4.5) for  $\langle(\Lambda_0 - \Lambda_D)\bar{g}_{\delta,t}, g_{\delta,t}\rangle$  with  $v_t$  being replaced by  $w_{\delta,t}$ , we get from (4.11) and decaying property of  $v_t$  that

$$\langle(\Lambda_0 - \Lambda_D)\bar{g}_{\delta,t}, g_{\delta,t}\rangle \leq C\alpha_2^{1/h}$$

for some  $0 < \alpha_2 < 1$ .

Now we first consider (i) of Theorem 4.1 for  $E_{\delta,t}(h)$ . We shall use a trick given in [4]. In view of the definition of the energy gap functional and the proof of the first inequality of (4.5), we get that

$$0 \leq \langle(\Lambda_0 - \Lambda_D)(\zeta\bar{f}_{\delta,t} \pm \zeta^{-1}\bar{g}_{\delta,t}), \zeta f_{\delta,t} \pm \zeta^{-1}g_{\delta,t}\rangle$$

for any  $\zeta > 0$ , which leads to

$$\begin{aligned} & |\langle(\Lambda_0 - \Lambda_D)\bar{f}_{\delta,t}, g_{\delta,t}\rangle + \langle(\Lambda_0 - \Lambda_D)\bar{g}_{\delta,t}, f_{\delta,t}\rangle| \\ & \leq \zeta^2\langle(\Lambda_0 - \Lambda_D)\bar{f}_{\delta,t}, f_{\delta,t}\rangle + \zeta^{-2}\langle(\Lambda_0 - \Lambda_D)\bar{g}_{\delta,t}, g_{\delta,t}\rangle. \end{aligned} \quad (4.12)$$

It now follows from  $v_t(x, h)|_{\partial\Omega} = f_{\delta,t} + g_{\delta,t}$  and (4.12) with  $\zeta = 1/\sqrt{2}$  that

$$\begin{aligned} & \frac{1}{2}\langle(\Lambda_0 - \Lambda_D)\bar{f}_{\delta,t}, f_{\delta,t}\rangle \\ & \leq \langle(\Lambda_0 - \Lambda_D)\bar{g}_{\delta,t}, g_{\delta,t}\rangle + \langle(\Lambda_0 - \Lambda_D)\bar{v}_t, v_t\rangle \\ & \leq C\alpha_2^{1/h} + \langle(\Lambda_0 - \Lambda_D)\bar{v}_t, v_t\rangle. \end{aligned} \quad (4.13)$$

So from (i) of Theorem 4.1, the same statement holds for  $E_{\delta,t}(h)$ . Likewise, the second inequality of (iii) in Theorem 4.1 also holds.

Next we consider (ii) and the first inequality of (iii) in Theorem 4.1 for  $E_{\delta,t}$ . Choosing  $\zeta = 1$  in (4.12) we get that

$$\begin{aligned} & \frac{1}{2}\langle(\Lambda_0 - \Lambda_D)\bar{v}_t, v_t\rangle \\ & \leq \langle(\Lambda_0 - \Lambda_D)\bar{g}_{\delta,t}, g_{\delta,t}\rangle + \langle(\Lambda_0 - \Lambda_D)\bar{f}_{\delta,t}, f_{\delta,t}\rangle \\ & \leq C\alpha_2^{1/h} + \langle(\Lambda_0 - \Lambda_D)\bar{f}_{\delta,t}, f_{\delta,t}\rangle. \end{aligned} \quad (4.14)$$

Therefore, (ii) of Theorem 4.1 and (4.14) implies that the same fact holds for  $E_{\delta,t}$ . Likewise, the first inequality of (iii) in Theorem 4.1 holds for  $E_{\delta,t}$ . The proof is now complete.  $\square$

**Remark 4.3.** *With the help of Theorem 4.2, when parts of  $\partial D$  are near the boundary  $\partial\Omega$ , we could detect some partial information of  $\partial D$  from only a few measurements taken from a very small region on one side of  $\partial\Omega$ .*

To end the presentation, we provide an algorithm of the method.

Step 1. Pick a point  $p \notin \bar{\Omega}$  and near  $\partial\Omega$ . Construct complex spherical waves  $v_t(x, h)$  for  $h \in S$ .

Step 2. Draw two balls  $B_t(p)$  and  $B_{t+\delta}(p)$ . Set the Dirichlet data  $f_{\delta,t} = \phi_{\delta,t} v_t|_{\partial\Omega}$ . Measure the Neumann data  $\Lambda_D f_{\delta,t}$  over the region  $B_{t+\delta}(p) \cap \partial\Omega$ .

Step 3. Calculate  $E_{\delta,t}(h) = \langle (\Lambda_0 - \Lambda_D) \bar{f}_{\delta,t}, f_{\delta,t} \rangle$ . If  $E_{\delta,t}(h)$  tends to zero as  $h \rightarrow 0$ , then the probing front  $\{|x - p| = t\}$  does not intersect the inclusion. Increase  $t$  and compute  $E_{\delta,t}(h)$  again.

Step 4. If  $E_{\delta,t}(h)$  increases to  $\infty$  as  $h \rightarrow 0$ , then the front  $\{|x - p| = t\}$  intersects the inclusion. Decrease  $t$  to make more accurate estimate of  $\partial D$ .

Step 5. Choose a different  $p$  and repeat the procedures Step 1-4.

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