

## 4 On numerical solution of hyperbolic PDEs

Consider a first order hyperbolic PDE

$$\begin{cases} \frac{\partial u}{\partial t} + a(x, t, u) \frac{\partial u}{\partial x} = g(x, t, u), & t > 0 \\ u(x, 0) = u_0(x), & -\infty < x < \infty. \end{cases} \quad (33)$$

Let us consider curves (“characteristics”) in  $t$ - $x$ -plane defined by the differential equation  $dx/dt = a(x, t, u)$ .

Along every characteristic  $x(t)$  the solution of (33) satisfies

$$\frac{du}{dt} = \frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} \frac{dx}{dt} = \frac{\partial u}{\partial t} + \frac{\partial u}{\partial x} a(x, t, u) = g(x, t, u).$$

A characteristic  $x$  and the value of the solution  $u$  on it can be calculated by solving ordinary differential equation system

$$\begin{cases} x'(t) = a(x, t, u), & x(0) = x_0 \\ u'(t) = g(x, t, u), & u(0) = u_0(x_0). \end{cases} \quad (34)$$

**Example 4.1.** Consider the problem

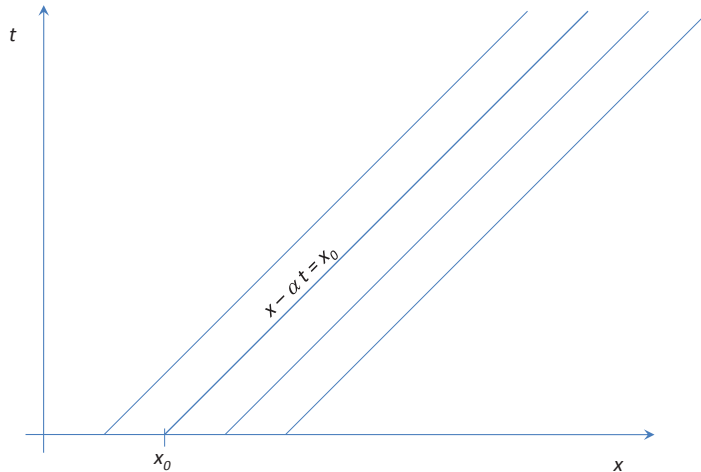
$$\frac{\partial u}{\partial t} + \alpha \frac{\partial u}{\partial x} = \beta, \quad \alpha \neq 0, \text{ and } \beta \text{ are constants.}$$

In this case (34) reads

$$\begin{cases} x'(t) = \alpha, & x(0) = x_0 \\ u'(t) = \beta, & u(0) = u_0(x_0). \end{cases}$$

This is easily solved resulting in  $x(t) = \alpha t + x_0$ ,  $u(t) = \beta t + u_0(x_0)$ . The solution of the original PDE along a characteristic is

$$\begin{aligned} u(x, t)|_{x-\alpha t=x_0} &= \beta t + u_0(x_0) \\ \implies u(x, t) &= \beta t + u_0(x - \alpha t) \quad \forall x, \forall t > 0. \end{aligned}$$



**Example 4.2.** Consider the problem

$$\frac{\partial u}{\partial t} + \alpha \frac{\partial u}{\partial x} = \beta u, \quad \alpha \neq 0, \text{ and } \beta \text{ are constants.}$$

In this case (34) reads

$$\begin{cases} x'(t) = \alpha, & x(0) = x_0 \\ u'(t) = \beta u, & u(0) = u_0(x_0). \end{cases}$$

This is again easily solved resulting in  $x(t) = \alpha t + x_0$ ,  $u(t) = u_0(x_0) e^{\beta t}$ . The solution of the original PDE along a characteristic is

$$\begin{aligned} u(x, t)|_{x-\alpha t=x_0} &= u(x_0) e^{\beta t} \\ \implies u(x, t) &= u_0(x - \alpha t) e^{\beta t} \quad \forall x, \forall t > 0. \end{aligned}$$

## 4.1 Finite difference approximation

Consider the simple hyperbolic PDE

$$\frac{\partial u}{\partial t} + a \frac{\partial u}{\partial x} = 0$$

with constant  $a > 0$ .

Forward difference in time:

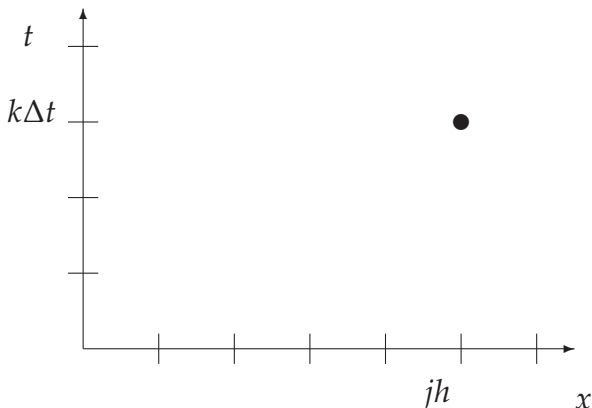
$$\frac{\partial u}{\partial t} = \frac{u_{k+1,j} - u_{k,j}}{\Delta t}.$$

Spatial discretization:

$$\frac{\partial u}{\partial x} = \frac{u_{k,j+\epsilon} - u_{k,j-\eta}}{(\epsilon + \eta)h}$$

Several formulas depending on the values of  $\epsilon, \eta$ , for example

$$\begin{aligned} \epsilon = 1, \eta = 1 & \quad \text{central difference } \mathcal{O}(h^2) \\ \epsilon = 1, \eta = 0 & \quad \text{forward difference } \mathcal{O}(h) \\ \epsilon = 0, \eta = 1 & \quad \text{backward difference } \mathcal{O}(h). \end{aligned}$$



What about the stability of the above schemes? Let's perform the von Neumann stability analysis, i.e. we assume that  $u_{k,j} = \zeta^k e^{ij\varphi}$ . Substituting this into the difference scheme above we obtain

$$\frac{\zeta^{k+1} e^{ij\varphi} - \zeta^k e^{ij\varphi}}{\Delta t} + a \cdot \frac{\zeta^k e^{i(j+\epsilon)\varphi} - \zeta^k e^{i(j-\eta)\varphi}}{(\epsilon + \eta)h} = 0. \quad (35)$$

Let us define the *Courant number*  $r := a \cdot \Delta t / h$ . Solving  $\zeta$  from (35) we obtain

$$\zeta = 1 - \frac{r}{\epsilon + \eta} \left( e^{i\epsilon\varphi} - e^{-i\eta\varphi} \right).$$

Now, the choices of  $\epsilon, \eta$  above result in:

$$\begin{aligned} \epsilon = \eta = 1 &\implies \zeta = 1 + ir \sin \varphi \implies \|\zeta\| \geq 1 \quad \forall r \\ \epsilon = 1, \eta = 0 &\implies \zeta = 1 + r - re^{i\varphi} \implies \|\zeta\| \geq 1 \quad \forall r \\ \epsilon = 0, \eta = 1 &\implies \zeta = 1 - r + re^{-i\varphi} \implies \|\zeta\| \leq 1 \quad \text{if } r \leq 1. \end{aligned}$$

Thus, only the combination “forward difference in time / backward difference in space” works provided that  $a \cdot \Delta t / h \leq 1$  (the Courant–Friedrichs–Levy condition, CFL).

### Lax–Wendroff scheme

This scheme is a modification of the unsuccessful  $\epsilon = \eta = 1$  scheme. It reads as

$$\frac{u_{k+1,j} - u_{k,j}}{\Delta t} + \frac{a}{2h} (u_{k,j+1} - u_{k,j-1}) - \frac{a^2 \Delta t}{2h^2} (u_{k,j+1} - 2u_{k,j} + u_{k,j-1}) = 0. \quad (36)$$

It can be shown that the accuracy of the scheme is  $\mathcal{O}(h^2 + (\Delta t)^2)$ . Once again, the stability limits the step sizes, i.e.  $r \leq 1$  should hold.

Notice that one can interpret this scheme by adding “artificial diffusion” to the original problem, i.e. we solve numerically the modified problem

$$\frac{\partial u}{\partial t} + a \frac{\partial u}{\partial x} - \frac{1}{2} a^2 \Delta t \frac{\partial^2 u}{\partial x^2} = 0.$$

## 4.2 Finite difference approximation of the wave equation

Consider the following wave equation in one space dimension:

$$\begin{cases} \frac{\partial^2 u}{\partial t^2} - c^2 \frac{\partial^2 u}{\partial x^2} = 0, & a < x < b, t > 0 \\ u(a, t) = \alpha(t), & u(b, t) = \beta(t) \\ u(x, 0) = f(x), & \frac{\partial u}{\partial t}(x, 0) = g(x). \end{cases} \quad (37)$$

Here  $\alpha, \beta, f, g$  are known functions.

We discretize both derivatives using central differences:

$$\frac{u_{k+1,j} - 2u_{k,j} + u_{k-1,j}}{(\Delta t)^2} - c^2 \frac{u_{k,j+1} - 2u_{k,j} + u_{k,j-1}}{h^2} = 0. \quad (38)$$

The numerical solution is obtained by marching in time by solving  $u_{k+1,j}$  from equation (38). This is depicted in Figure 2 (the black nodal value is computed using the white ones). In order to start the marching process, a small trick is needed. Artificial values  $u_{-1,j}$  are obtained by taking into account the initial conditions:

$$\frac{u_{1,j} - u_{-1,j}}{2\Delta t} = g(x_j), \quad u_{0,j} = f(x_j).$$

The accuracy of the leapfrog method is  $\mathcal{O}(h^2 + (\Delta t)^2)$  and the CFL condition  $c\Delta t/h \leq 1$  must hold.

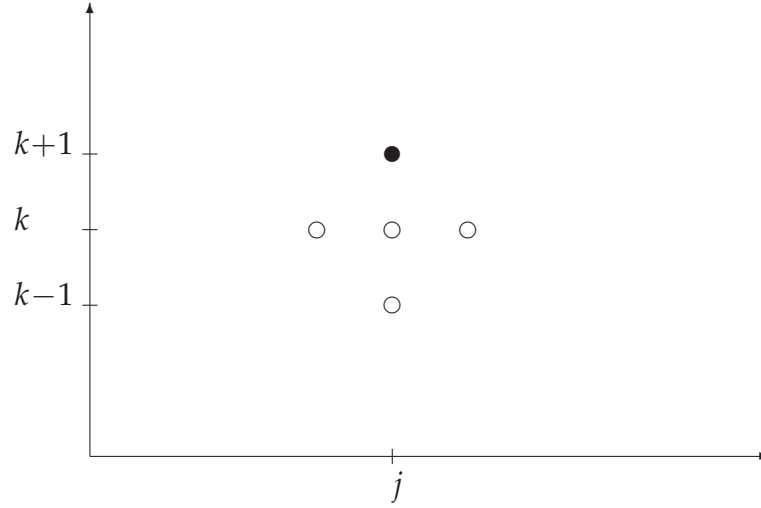


Figure 2: Leap frog scheme

### 4.3 On the nature of the solution of the wave equation

Consider the following wave equation in an unbounded domain

$$\begin{cases} \frac{\partial^2 u}{\partial t^2} - c^2 \frac{\partial^2 u}{\partial x^2} = 0, & -\infty < x < \infty, t > 0 \\ u(x, 0) = f(x), & \frac{\partial u}{\partial t}(x, 0) = g(x). \end{cases} \quad (39)$$

The analytical solution to (39) is

$$u(x, t) = \frac{1}{2}f(x + ct) + \frac{1}{2}f(x - ct) + \frac{1}{2c} \int_{x-ct}^{x+ct} g(s) ds.$$

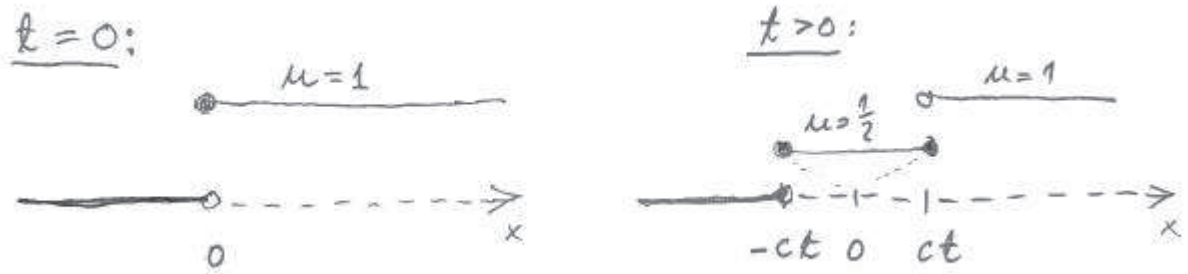
If  $g \equiv 0$  then

$$u(x, t) = \frac{1}{2}f(x + ct) + \frac{1}{2}f(x - ct).$$

Thus the information of the initial condition spreads with constant speed  $c$  along *two* characteristics.

**Example 4.3.** Let  $g \equiv 0$  and

$$f(x) = \begin{cases} 1, & x > 0 \\ 0, & \text{otherwise.} \end{cases}$$



From the picture  
we see that the “information” (discontinuity at  $x = 0$ ) travels to two directions at speed  $c$ .