

Let  $\mathcal{F} : \mathbb{R}^n \rightarrow \mathbb{R}^n$  be a vector valued function. Nonlinear algebraic system of equations  $\mathcal{F}(x) = 0$  can be solved using Newton's method

$$x^{(k+1)} = x^{(k)} - [\mathcal{J}(x^{(k)})]^{-1} \mathcal{F}(x^{(k)}), \quad k = 0, 1, 2, \dots$$

Here  $\mathcal{J}(x^{(k)})$  is the Jacobian of  $\mathcal{F}$  at  $x^{(k)}$ . Thus, at each Newton iteration one has to solve a linear system of equations. If the Jacobian is large and sparse one can use e.g. GMRES method to solve it. This linear system can be solved without forming the matrix  $\mathcal{J}$  explicitly. Namely from Taylor expansion  $\mathcal{F}(x + \epsilon v) \approx \mathcal{F}(x) + \epsilon \mathcal{J}(x)v$  it follows that the matrix-vector product needed in GMRES can be approximated by

$$\mathcal{J}(x)v \approx \frac{1}{\epsilon} (\mathcal{F}(x + \epsilon v) - \mathcal{F}(x)).$$