

Quantum mechanical tomography and neutrino oscillation

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1 Neutrino oscillation

- Neutrinos
- Schrödinger's equation and mass
- Oscillation
- Matter effects

2 Quantum mechanical tomography

Neutrinos

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- There are three generations of neutrinos corresponding to the charged leptons:
 - the electron neutrino ν_e
 - the muon neutrino ν_μ
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- Neutrino masses are $\lesssim 1$ eV. (Natural units: $c = \hbar = 1$.) For comparison, the masses of an electron and a neutron are $5 \cdot 10^5$ eV and $2 \cdot 10^9$ eV.

Schrödinger's equation and mass

- We can think of neutrinos as point particles. The state of a neutrino is

$$\Psi(x, t) = \begin{pmatrix} \Psi_{\nu_e}(x, t) \\ \Psi_{\nu_\mu}(x, t) \\ \Psi_{\nu_\tau}(x, t) \end{pmatrix} \in \mathbb{C}^3.$$

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- We need an equation of motion for $\Psi(x, t)$.

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- In vacuum we obtain the ultrarelativistic Schrödinger equation

$$i\partial_t\Psi(x,t) = \left(p + \frac{1}{2p}M^2\right)\Psi(x,t),$$

where M is the neutrino mass matrix.

- If the neutrinos ν_e, ν_μ, ν_τ had masses $m_{\nu_e}, m_{\nu_\mu}, m_{\nu_\tau}$, the mass matrix would be

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 - the flavor basis consisting of flavor states ν_e, ν_μ and ν_τ ,
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The basis can be changed via the PMNS matrix U .

Oscillation

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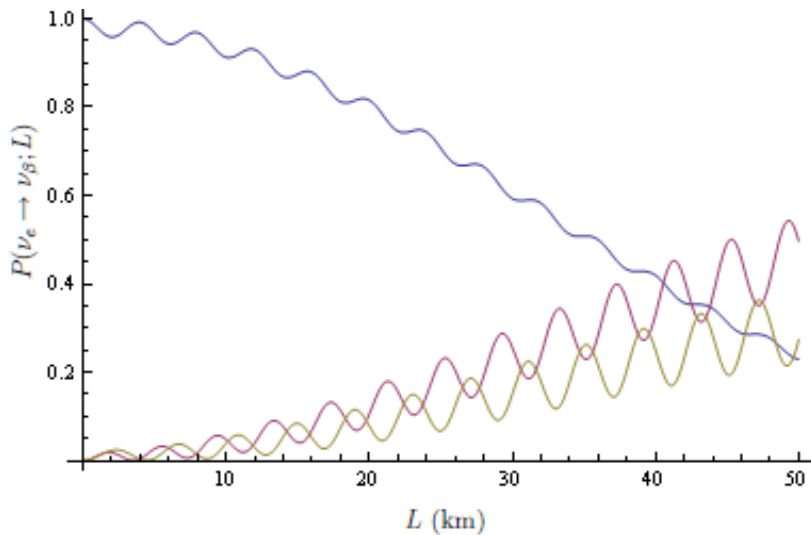
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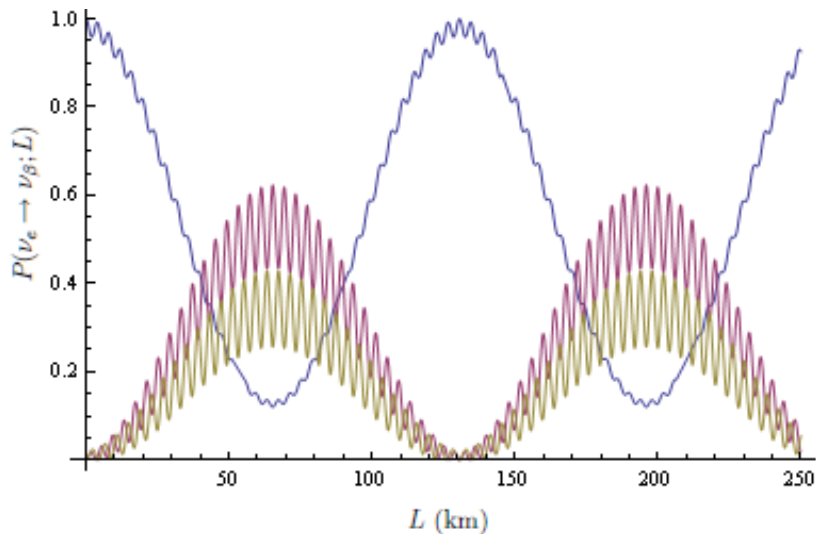
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- Different mass states have slightly different velocities and therefore they slowly drift apart. They lose coherence and no longer oscillate. We will focus on coherent phenomena.

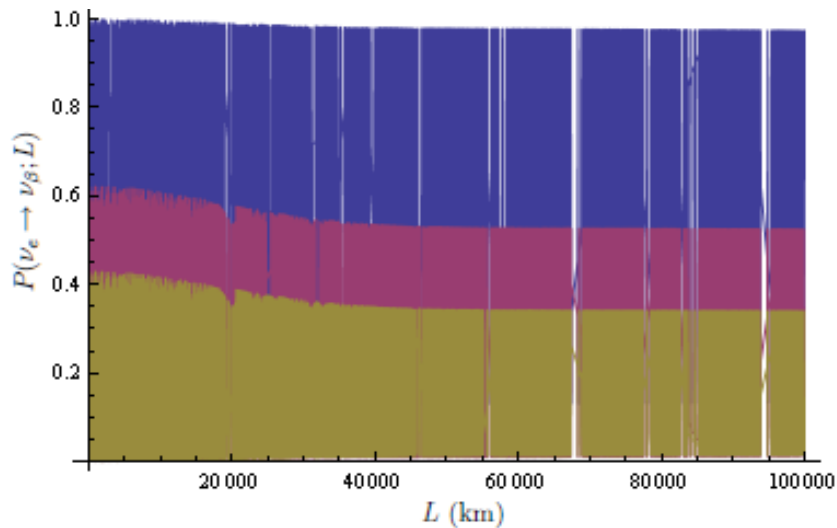
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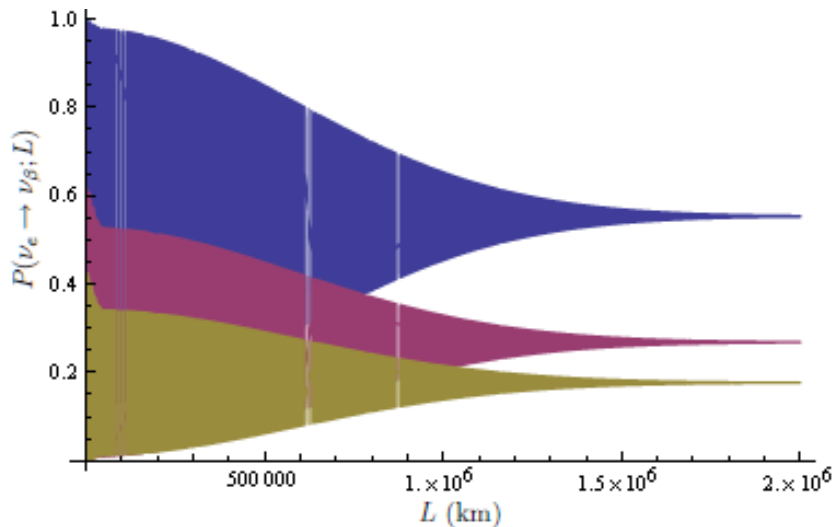
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Matter effects

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- The oscillation is not a dynamical phenomenon, but a kinematical one. No interaction is involved.
- Interactions with the background change the oscillation.
- **Question:** Can we reconstruct the background from neutrino oscillation data?

- 1 Neutrino oscillation
- 2 Quantum mechanical tomography
 - The model
 - The data
 - The problem
 - The result
 - X-ray transforms with matrix weights

The model

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- The particle travels with constant speed v , $|v| = 1$, through a domain $\Omega \subset \mathbb{R}^n$. (Classical point particle.)
- The Hamilton matrix $H(x) \in \mathbb{C}^{N \times N}$ depends on $x \in \Omega$.
- The time evolution of a state $\Psi(t) \in \mathbb{C}^N$ along the trajectory $t \mapsto x_0 + tv$ is given by $i\partial_t \Psi(t) = H(x_0 + tv)\Psi(t)$.

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- For neutrinos, both sets are the flavor basis (three orthogonal unit vectors in \mathbb{C}^3).
- We measure this number $|\langle f, \Psi(T) \rangle|^2$ for all initial states $\Psi(0)$, all reference states f and all trajectories through Ω .

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- For positive results we need to assume “ideal data”.
 - Example: All states in \mathbb{C}^N are available as initial and reference states.
 - Non-example: Neutrino oscillation data.

The result

Theorem (I., 2015)

Let $\Omega \subset \mathbb{R}^n$, $n \geq 3$, be a bounded convex domain. Let $N \geq 1$ be an integer and suppose $H, \tilde{H} \in C^{1,\alpha}(\bar{\Omega}, \mathbb{C}^{N \times N})$ for some $\alpha > 0$ are pointwise hermitean.

Assume ideal data in the described measurements. The two Hamiltonians H and \tilde{H} give the same data if and only if $\tilde{H} = H + \phi I$ for a scalar function ϕ .

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- The weighted integral of a function $f: \bar{\Omega} \rightarrow \mathbb{C}^M$ over a smooth unit speed curve $\gamma: [0, T] \rightarrow \bar{\Omega}$ is

$$\int_0^T W(\gamma(t), \dot{\gamma}(t)) f(\gamma(t)) dt.$$

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Theorem (I., 2015)

Let $\Omega \subset \mathbb{R}^n$, $n \geq 3$, be a bounded convex domain. If W is $C^{1,\alpha}$ for some $\alpha > 0$ and pointwise invertible, then a continuous $f: \bar{\Omega} \rightarrow \mathbb{C}^M$ is uniquely determined by its weighted integrals over all straight lines.

J. Ilmavirta: **Coherent quantum tomography**, preprint,
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Thank you.