

Weak solutions to the master equation of potential mean field games

Seminar on SDEs and related topics

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May 6 2022

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1. Mean field games and related master equation

Background

- **Originates from** macroeconomics: games with many many heterogeneous rational agents
 - associate **cost functional** with each player
 - interactions through **aggregated** quantity: say price...
 - each agent has nearly infinitesimal impact but the sum of all forms a compromise!
 - advocate for games with a **continuum** of players

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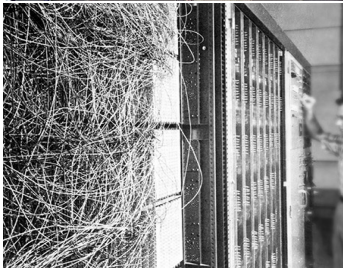
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 - advocate for games with a **continuum** of players
- **Paradigm for games with a continuum of players** [Aumann, 64]
 - taken from **mean-field approach** in statistical mechanics \rightsquigarrow players interact one with the others through the **theoretical** distribution of the population
 - solving games is computationally demanding, but asymptotic formulation under mean-field assumption has **lower complexity**

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 - taken from Von Neumann and Morgenstern:

this is a well known phenomenon in many branches of the exact and physical sciences that very great numbers are often easier to handle than those of medium size. This is of course due to the excellent possibility of applying the laws of statistics and probabilities in the first case

Typical examples...



Matching problem of MFG

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(1) fix a flow of probability measures $(\mu_t)_{0 \leq t \leq T}$ (with values in $\mathcal{P}_2(\mathbb{R}^d)$)

(2) solve the stochastic optimal control problem in the environment $(\mu_t)_{0 \leq t \leq T}$

$$dX_t = \alpha_t dt + dW_t$$

◦ with $X_0 = \xi$ being fixed on some set-up $(\Omega, \mathbb{F}, \mathbb{P})$ with a d -dimensional B.M.

◦ with cost $J(\alpha) = \mathbb{E} \left[g(X_T, \mu_T) + \int_0^T (f(X_t, \mu_t) + \frac{1}{2} |\alpha_t|^2) dt \right]$

◦ example: $f(x, \mu) = \int_{\mathbb{R}^d} h(x - y) d\mu(y)$

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(3) let $(X_t^{\star, \mu})_{0 \leq t \leq T}$ be the unique optimizer (under nice assumptions)
 \leadsto find $(\mu_t)_{0 \leq t \leq T}$ such that

$$\mu_t = \mathcal{L}(X_t^{\star, \mu}), \quad t \in [0, T]$$

- [Lasry-Lions], [Caines-Huang-Malhamé]...

PDE point of view

- Value function in environment $(\mu_t)_{0 \leq t \leq T}$

$$u(t, x) = \inf_{\alpha \text{ processes}} \mathbb{E} \left[g(X_T, \mu_T) + \int_t^T \left(f(X_s, \mu_s) + \frac{1}{2} |\alpha_s|^2 \right) ds \mid X_t = x \right]$$

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◦ u solution Backward HJB

$$\left(\partial_t u + \frac{1}{2} \Delta_x u \right)(t, x) + \underbrace{\inf_{\alpha \in \mathbb{R}^d} [\alpha \cdot \partial_x u(t, x) + \frac{1}{2} |\alpha|^2 + f(x, \mu_t)]}_{\text{standard Hamiltonian in HJB}} = 0$$

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- u solution Backward HJB

$$\left(\partial_t u + \frac{1}{2} \Delta_x u \right)(t, x) - \frac{1}{2} |\partial_x u(t, x)|^2 + f(x, \mu_t) = 0$$

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- terminal boundary condition: $u(T, \cdot) = g(\cdot, \mu_T)$
- Pay attention that u depends on $(\mu_t)_t$!

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- terminal boundary condition: $u(T, \cdot) = g(\cdot, \mu_T)$
 - Pay attention that u depends on $(\mu_t)_t$!
- Need for a PDE characterization of $(\mathcal{L}(X_t^{\star, \mu}))_t$
 - Dynamics of $X^{\star, \mu}$ at equilibrium

$$dX_t^{\star, \mu} = -\partial_x u(t, X_t^{\star, \mu}) dt + dW_t$$

- Law $(X_t^{\star, \mu})_{0 \leq t \leq T}$ satisfies Fokker-Planck (FP) equation

$$\partial_t \mu_t = \operatorname{div}_x (\partial_x u(t, x) \mu_t) + \frac{1}{2} \Delta_x \mu_t$$

- End-up with forward-backward system in ∞ dimension

Master equation

- A lot on the **MFG forward-backward system** [Cardaliaguet and Porretta] \leftrightarrow **McKean Vlasov** [FBSDE]
- A key point of view \leadsto regard **MFG system** as the **characteristics of a PDE** on space of probability measures
 - look for $v(t, x, m)$, with $m \in \mathcal{P}(\mathbb{R}^d)$ such that

$$u_t(x) = v(t, x, m_t)$$

- $v(t, x, m)$ is **the** (???) equilibrium value of the game with (t, m) as initial state

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- $v(t, x, m)$ is **the** (???) equilibrium value of the game with (t, m) as initial state
 - formal proof is to expand $v(t, x, m_t)$ by chain rule and to identify with the expansion of $u_t(x)$

$$\begin{aligned} & d[v(s, X_s^\star, \mathcal{L}(X_s^\star))] \\ &= \left[f(X_s^\star, \partial_x v(s, X_s^\star, \mathcal{L}(X_s^\star))) + \frac{1}{2} |\partial_x v(s, X_s^\star, \mathcal{L}(X_s^\star))|^2 \right] ds \\ & \quad + \partial_x v(t, X_s^\star, \mathcal{L}(X_s^\star)) dB_s \end{aligned}$$

- $X_t^\star \sim m$

Master equation

- Look for $v(t, x, m)$, with $m \in \mathcal{P}(\mathbb{R}^d)$ such that

$$u_t(x) = v(t, x, m_t)$$

- Equation for $v(t, x, m)$ with $x \in \mathbb{R}^d$ and $m \in \mathcal{P}(\mathbb{R}^d)$

$$\begin{aligned} & \partial_t v(t, x, m) - \frac{1}{2} |\partial_x v(t, x, m)|^2 + \frac{1}{2} \Delta_x v(t, x, m) + f(x, m) \\ & - \frac{1}{2} \int \partial_x v(t, y, m) \partial_\mu v(t, x, m)(y) dm(y) \\ & + \frac{1}{2} \int \text{Tr}(\partial_y \partial_\mu v(t, x, m)(y)) dm(y) = 0 \end{aligned}$$

- definition of the derivative

$$\partial_\mu v(t, x, m)(y) = \partial_y \frac{\delta v}{\delta m}(t, x, m)(y)$$

$$\frac{\delta v}{\delta m}(t, x, m)(y) = \lim_{\varepsilon \searrow 0} \frac{v(t, x, (1 - \varepsilon)m + \varepsilon \delta_y) - v(t, x, m)}{\varepsilon}$$

Master equation

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\leadsto blue part is HJB; red terms are mean field

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- Smoothness in x is ok (thanks to Δ_x) but **smoothness in m is an issue**: infinite dimensional hyperbolic system

Bibliography

- Classical solutions to the master equation under **monotonicity** [same for g]

$$\int_{\mathbb{R}^d} (f(x, \mu) - f(x, \mu')) d(\mu - \mu')(x) \geq 0$$

Bibliography

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$$\int_{\mathbb{R}^d} (f(x, \mu) - f(x, \mu')) d(\mu - \mu')(x) \geq 0$$

- smooth coefficients [Cardaliaguet, D., Lasry, Lions], [Chassagneux, Crisan, D.] (see also [Buckdahn, Li, Peng, Rainer])
- research on master equation in weaker setting (Bertucci, Mou & Zhang, Gangbo & Meszaros...)

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- **How to go beyond monotonicity?** \leadsto potential games

- MFG solutions are critical points of a **mean field control problem**: control problem with trajectories taking values in $\mathcal{P}(\mathbb{R}^d)$

- solve first HJ equation and say that MFG system is the derivative of the HJ equation

- identify the solution of the master equation with the derivative of the value function (finite dimension: [Kruzhkov, Lions])

2. Mean field control: optimal control of McKean Vlasov equations

Potential mean field game

- Mean field game

$$dX_t = \alpha_t dt + dB_t$$

$$J(\alpha) = \mathbb{E} \int_0^T \left(f(X_t, \mu_t) + \frac{1}{2} |\alpha_t|^2 \right) dt + \mathbb{E} g(X_T, \mu_T)$$

- α_t = control, μ = environment

- No monotonicity but potential (below same for g/G)

$$f(x, \mu) = \frac{\delta F}{\delta m}(\mu)(x) = \lim_{\varepsilon \searrow 0} \frac{F((1 - \varepsilon)\mu + \varepsilon \delta_x) - F(\mu)}{\varepsilon}$$

- flat derivative (defined up to a constant: centred w.r.t. m)

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- flat derivative (defined up to a constant: centred w.r.t. m)

- Derives from a mean field control problem!

Mean field control problem

- Same state dynamics but \neq optimization

$$dX_t = \alpha_t dt + dB_t$$

$$J(\alpha) = \int_0^T \left(F(\mu_t) + \frac{1}{2} \mathbb{E}(|\alpha_t|^2) \right) dt + G(\mu_T)$$

- $\mu_t = \mathcal{L}(X_t)$ (law of X_t)
- this is a McKean-Vlasov problem: the fixed point condition is fixed before the optimization step and not after!

Mean field control problem

- PDE formulation

$$\partial_t \mu_t(x) + \operatorname{div}_x(\alpha_t(x) \mu_t(x)) - \frac{1}{2} \Delta_x \mu_t(x) = 0$$

$$J(\alpha) = \int_0^T \left(F(\mu_t) + \frac{1}{2} \int_{\mathbb{R}^d} |\alpha_t(x)|^2 \right) dt + G(\mu_T)$$

- Pontryagin principle \Rightarrow MFG system is the first-order condition
[Lasry-Lions], [Briani-Cardaliaguet]

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- Value function $V(t, m) \rightsquigarrow$ minimal cost when $\mathcal{L}(X_t) = m$
- HJ equation

$$\left\{ \begin{array}{l} \partial_t V(t, m) - \frac{1}{2} \int |\partial_\mu V(t, m)(y)|^2 dm(y) \\ \quad + \frac{1}{2} \int \operatorname{Tr}(\partial_y \partial_\mu V(t, m)(y)) dm(y) + F(m) = 0 \\ V(T, m) = G(m) \end{array} \right.$$

- No smooth solution in general setting; theory of viscosity solutions still in development \rightsquigarrow main difficulty: Δ , see [Pham and co-authors, Conforti and co-authors]

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- **Objective: write a generalized form** ('a.e. derivatives') and uniqueness for semi-concave solutions

Using Fourier analysis

- Provide a notion of **generalized solution to HJB** based on finite dimensional Fourier approximations

- use **periodic setting and get discretization with respect to Fourier coefficients**

$$\mathcal{P}(\mathbb{R}^d) \Rightarrow \mathcal{P}(\mathbb{T}^d)$$

and

$$\phi(m), \quad m \in \mathbb{T}^d \Rightarrow \phi\left(\left(\widehat{m}^k\right)_k\right), \quad \widehat{m}^k = \int_{\mathbb{T}^d} e^{i2\pi k \cdot x} dm(x)$$

- restrict functions to measures m such that

$$\widehat{m}^k = 0 \quad \text{if} \quad |k| \geq N, \quad \text{for some } N \geq 1$$

- Good point because those measures are stable by the heat equation which is the characteristic equation of the operator

$$\left(\phi : \mathcal{P}(\mathbb{T}^d) \rightarrow \mathbb{R}\right) \mapsto \frac{1}{2} \int_{\mathbb{T}^d} \text{Tr}\left(\partial_y \partial_\mu \phi(m)(y)\right) dm(y)$$

Finite dimensional restrictions

- For $\phi : \mathcal{P}(\mathbb{T}^d) \rightarrow \mathbb{R}$, **restrict** to

$$O_N = \left\{ m \in \mathcal{P}(\mathbb{T}^d) : \hat{m}^k = 0, \max_{j=1, \dots, d} |k_j| \geq N \right\}$$

- **Bochner-Herglotz**: \exists density f_N s.t. $f_N * m \in O_N$ for $m \in \mathcal{P}(\mathbb{T}^d)$

- If ϕ is Lipschitz for total variation

$$| \phi(m_1) - \phi(m_2) | \leq C \int_{\mathbb{T}^d} |m_1(x) - m_2(x)| dx \leq C \left(\sum_{\max_{j=1, \dots, d} |k_j| < N} |\widehat{m}_1^k - \widehat{m}_2^k|^2 \right)^{1/2}$$

- **restriction of ϕ is a.e. differentiable on O_N**
- identification of $(\widehat{\delta\phi/\delta m})^k$ for $\max_{j=1, \dots, d} |k_j| < N$

$$\begin{aligned} \frac{d}{d\varepsilon} \Big|_{\varepsilon=0} \phi\left((\widehat{m}^k + \varepsilon \widehat{r}^k)_k\right) &= \sum_{\max_{j=1, \dots, d} |k_j| < N} (\widehat{\delta\phi/\delta m})^{-k} \widehat{r}^k \\ \leadsto \partial_{\widehat{m}^k / \widehat{m}^k} \phi &= (\widehat{\delta\phi/\delta m})^{-k} \end{aligned}$$

Application to HJ

- Standard property: value function V is time-space Lipschitz (for even coarser topologies)
- Write HJB at a point $(t, m) \in [0, T] \times \mathcal{O}_N$ at which the restriction of V is differentiable

\leadsto we have $\partial_{\widehat{m}^k} V(t, m)$ for $\max_{j=1, \dots, d} |k_j| < N$

- Philosophy: rewrite the terms as derivatives w.r.t. Fourier coefficients

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$$\leadsto \frac{1}{2} \int_{\mathbb{T}^d} \text{Tr} \left(\partial_y \partial_\mu V(t, m)(y) \right) dm(y) = \frac{1}{2} \int_{\mathbb{T}^d} \Delta_y \frac{\delta}{\delta m} V(t, m)(y) dm(y)$$

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$$\leadsto -\frac{1}{2} \int_{\mathbb{T}^d} \left| \partial_\mu V(t, m)(y) \right|^2 dm(y) \Rightarrow \text{ALL the Fourier modes of } \partial_\mu V$$

$$-\frac{1}{2} \int_{\mathbb{T}^d} \left| \partial_\mu V(t, m)(y) \right|^2 dm(y) \simeq -\frac{1}{2} \int_{\mathbb{T}^d} \left| \sum_{|k_j| < N} k \partial_{\widehat{m}^k} V(t, m) e^{i2\pi k \cdot y} \right|^2 dm(y)$$

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- By Pontryagin principle $\partial_{\widehat{m}^k} V(t, m) = u_0^{-k} \Rightarrow$ known decay with k

Reformulation of HJ

- **General formulation** (for V Lipschitz, not being necessarily the value function)

- require for any N and a.e. $(t, m) \in [0, T] \times \mathcal{O}_N$

$$\begin{aligned} \partial_t V(t, m) - \sum_{|k_j| < N} 2\pi^2 |k|^2 \widehat{m}^k \partial_{\widehat{m}^k} V(t, m) \\ - \frac{1}{2} \int \left| \sum_{|k_j| < N} k \partial_{\widehat{m}^k} V(t, m) e^{i2\pi k \cdot y} \right|^2 dm(y) + F(m) = O(\eta_N) \end{aligned}$$

$\leadsto \eta_N$ converges to 0 and notation $O(\cdot)$ is (almost) uniform on $[0, T] \times \mathcal{O}_N$

- Result 1: **The value function satisfies the general formulation**
 - use DPP...
- Question: **uniqueness?**

Scheme for uniqueness

- General idea: V_1 and V_2 two solutions

- if **classical** $\Rightarrow V_1 - V_2$ satisfies

$$\begin{aligned} \partial_t[V_1 - V_2](t, m) + \frac{1}{2} \int \text{Tr}(\partial_y \partial_\mu[V_1 - V_2](t, m)(y)) dm(y) \\ - \int \frac{1}{2} (\partial_\mu V_1 + \partial_\mu V_2)(t, m)(y) (\partial_\mu[V_1 - V_2])(t, m)(y) dm(y) = 0 \end{aligned}$$

- solve Fokker-Planck equation/McKean-Vlasov equation

$$\begin{aligned} \partial_t \mu_t(x) + \text{div}_x \left[\frac{1}{2} (\partial_\mu V_1 + \partial_\mu V_2)(t, \mu_t)(x) \mu_t(x) \right] dt - \frac{1}{2} \Delta_x \mu_t(x) = 0 \\ dX_t = -\frac{1}{2} (\partial_\mu V_1 + \partial_\mu V_2)(t, \mathcal{L}(X_t))(X_t) dt + dB_t \end{aligned}$$

- expand $(V_1 - V_2)(t, \mu_t)$ in time and get

$$[V_1 - V_2](0, \mu_0) = 0$$

- Question: **When generalized solutions?**

Mollified HJ equation

- Claim: If V is a generalized solution, then **mollification** that **nearly solves** HJ in classical sense \Rightarrow **mollification parameters**:

$\leadsto N$: **truncation** of Fourier coefficients of m in V

$\leadsto \varrho_N$: **finite-dimensional** mollification kernel on Fourier coefficients up to order N (**mollification for a given truncation**)

- Statement: If V is generalized solution, then $\exists V^{N, \varrho_N} \sim V$ such that

$$\begin{aligned} & \partial_t V^{N, \varrho_N}(t, m) - \frac{1}{2} \int |\partial_\mu V^{N, \varrho_N}(t, m)(y)|^2 dm(y) \\ & + \frac{1}{2} \int \text{Tr}(\partial_y \partial_\mu V^{N, \varrho_N}(t, m)(y)) dm(y) + F(m) = O(\eta_N) + \phi_t^{N, \varrho_N}(m) \end{aligned}$$

- $\eta_N \rightarrow 0$ (independently of ϱ_N)
- $\phi_t^{N, \varrho_N}(m)$ depends on \widehat{m}^k for $\max_{j=1, \dots, d} |k_j| < N$ and in L^1

$$\int |\phi_t^{N, \varrho_N}(m)| d(\widehat{m}^k)_{|k_j| < N} \rightarrow 0 \quad \text{as } \varrho_N \rightarrow \delta_0 \quad (N \text{ fixed})$$

Back to uniqueness

- Proceed as before and now compare $V_1^{N,\varrho_N} - V_2^{N,\varrho_N} \Rightarrow$
Fokker-Planck equation

$$\partial_t \mu_t(x) + \operatorname{div}_x \left[\frac{1}{2} \left(\partial_\mu V_1^{N,\varrho_N} + \partial_\mu V_2^{N,\varrho_N} \right) (t, \mu_t)(x) \mu_t(x) \right] dt - \frac{1}{2} \Delta_x \mu_t(x) \sim 0$$

- with solutions in \mathcal{O}_N
then

$$\left(V_1^{N,\varrho_N} - V_2^{N,\varrho_N} \right) (0, \mu_0) = O(\eta_N) + \int_0^T \phi_t^{N,\varrho_N}(\mu_t) dt$$

- difficult term is $\phi_t^{N,\varrho_N}(\mu_t)$: $\phi_t^{N,\varrho_N}(\cdot) \rightarrow 0$ in L^1 (taking as inputs $(\hat{m}_k)_{|k_j| < N}$)

- need to consider $(\widehat{\mu}_t^k)_{|k_j| < N}$:

If $(\widehat{\mu}_0^k)_{|k_j| < N}$ are chosen randomly according to a bounded density

\Rightarrow the density of $(\widehat{\mu}_t^k)_{|k_j| < N}$ remains bounded (indep. of ϱ_N)

Need for semi-concavity

- Need to control the **contraction** of the Fourier coefficients of the solution to MKV equation
 - semi-concavity comes in

$$V(t, \mathcal{L}(X + Y)) + V(t, \mathcal{L}(X - Y)) - 2V(t, \mathcal{L}(X)) \leq C\mathbb{E}[|Y|^2]$$

- Result 2: **Uniqueness of Lipschitz, semi-concave generalized solutions such that**

$$\partial_{\widehat{m}^k} V(t, m)$$

decreases fast enough at points where the derivative exists

\leadsto covers the value function

3. Back to mean field games

Back to the master equation

- Recall the master equation

$$\begin{aligned} \partial_t v(t, x, m) - \frac{1}{2} |\partial_x v(t, x, m)|^2 + \frac{1}{2} \Delta_x v(t, x, m) + f(x, m) \\ - \frac{1}{2} \int \partial_x v(t, y, m) \partial_\mu v(t, x, m)(y) dm(y) \\ + \frac{1}{2} \int \text{Tr}(\partial_x \partial_\mu v(t, x, m)(y)) dm(y) = 0 \end{aligned}$$

- Conservative form

\leadsto if v smooth then $\bar{v} = v - \int v dm$ solves

$$\begin{aligned} \partial_t \bar{v}(t, x, m) - \frac{1}{2} \frac{\delta}{\delta m} \left[\int |\partial_y \bar{v}(t, y, m)|^2 dm(y) \right] (x) \\ + \frac{1}{2} \frac{\delta}{\delta m} \left\{ \int \text{Tr}(\partial_y^2 \bar{v}(t, y, m)) dm(y) \right\} (x) + \frac{\delta F}{\delta m}(x) = 0 \end{aligned}$$

\leadsto guess: $\bar{v}(t, x, m) = \frac{\delta V}{\delta m}(t, m)(x)$

Generalized solution

- Bounded measurable function

$$\mathcal{Z} : [0, T] \times \mathcal{P}(\mathbb{T}^d) \times \mathbb{T}^d \rightarrow \mathbb{R}^d,$$

such that the **system of Fourier coefficients**

$$\widehat{\mathcal{Z}}^k : [0, T] \times \mathbb{P}(\mathbb{T}^d) \ni (t, m) \mapsto Z(\widehat{t, m}, \cdot)^{-k},$$

satisfies for $N \geq 1$, for $\max_{j=1, \dots, d} |k_j| < N$, **a.e. on O_N**

$$\begin{aligned} & \partial_t \widehat{\mathcal{Z}}^k(t, m) - 2\pi^2 \partial_{\widehat{m}^k} \int_{\mathbb{T}^d} \left| \sum_{|k_j| < N} j \widehat{\mathcal{Z}}^j(t, m) e_j(y) \right|^2 dm(y) \\ & - \sum_{|k_j| < N} 2\pi^2 |j|^2 \partial_{\widehat{m}^k} \widehat{\mathcal{Z}}^j(t, m) \widehat{m}^j + \widehat{f}^{-k}(m, \cdot) + \partial_{\widehat{m}^k} (\eta_N(t, m)) = 0 \end{aligned}$$

with $\eta_N \rightarrow 0$ (almost) uniformly on $[0, T] \times O_N$

Uniqueness

- Claim: **Uniqueness of generalized functions** that satisfy a weak one-sided Lipschitz property
 - weak solutions derive from a potential on O_N and this potential is semi-concave
- Some care is needed to aggregate all the equations (for any truncation N)
 - \exists probability measure \mathbb{P} on $\mathcal{P}(\mathbb{T}^d)$ **with full support** such that uniqueness holds a.e. under \mathbb{P} for solutions \mathcal{Z} such that

$$\widehat{\mathcal{Z}}^k(t, m * f_N) \rightharpoonup \widehat{\mathcal{Z}}^k(t, m)$$

weakly (when test with respect to bounded functions depending on a finite number of Fourier coefficients)

- **derivative of HJB satisfies the requirements**
- Short look at construction of \mathbb{P} : \mathbb{P} is the weak limit of

$$d\mathbb{P}_N(m) = 1_{O_N}(m) \frac{1}{Z_N} \exp\left(- \sum_{|k_j| < N} |k|^{2pd} |\widehat{m}^k|^2\right) \prod_{|k_j| < N} d\widehat{m}^k$$