

Old And New Algorithms for Minimal Coverability Sets

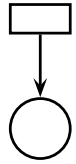
Petri Nets 2012, Hamburg

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1 Minimal Coverability Sets

The set of reachable markings of a Petri net is not necessarily finite



Karp & Miller 1969: Coverability set

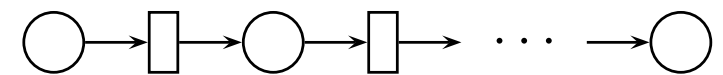
- $M(p) = \omega$ denotes that the marking of place p may grow without limit
- when $M [t_1 \cdots t_n \rangle M' > M$ and $M(p) < M'(p) < \omega$, replace $M'(p)$ by ω

Properties

- for every reachable marking M , the set has an ω -marking M' s.t. $M \leq M'$
- for every M' in the set and every $n \in \mathbb{N}$, there is a reachable M such that $M(p) = M'(p) < \omega$ or $M(p) \geq n \wedge M'(p) = \omega$
- **finite**, but **not unique**

Finkel 1993: Minimal Coverability Set

- keep only maximal ω -markings
- ! do so even if the marking is ordinary



Minimal coverability sets may be very big

- n places, $n - 1$ tokens in the leftmost: $\approx 2^{2n-2} / \sqrt{\pi(n-1)}$ ω -markings

Geeraerts & Raskin & Van Begin 2010, Reynier & Servais 2011, ...:
complicated algorithms

2 Mathematical Properties

Clarified proofs — not yet algorithms or even transitions

All M are ω -markings, unless otherwise stated

Every growing sequence $M_1 \leq M_2 \leq \dots$ has a limit

- for each p , either $M(p) = M_i(p) = M_{i+1}(p) = \dots$ from some i on, or $M(p) = \omega$ and $M_i(p)$ grows without a limit

We define a limit of a set as any limit of a growing sequence of its elements

- every element of the set is a limit, because $M \leq M \leq \dots$

Lemma The limit of any growing sequence of limits is a limit.

- the lemma can be applied $\leq |P|$ times in a row
 \Rightarrow each set is covered by its maximal limits

Lemma (follows from Dickson's, easier to prove directly)

Every infinite sequence of ω -markings has an infinite growing subsequence.

- proof: construct one place at a time, by picking from previous sequence

Let $[\mathcal{M}]$ be the limits of \mathcal{M} and $\lceil \mathcal{M} \rceil$ be the maximal elements of $[\mathcal{M}]$

Theorem $\lceil \mathcal{M} \rceil$ is finite and the only minimal coverability set.

3 Overview of New Algorithm

```
1   $F := \{\hat{M}\}; A := \{\hat{M}\}; W := \{\hat{M}\} \times T; \hat{M}.B := \text{nil}$ 
2  while  $W \neq \emptyset$  do
3       $(M, t) := \text{any element of } W; W := W \setminus \{(M, t)\}$ 
4      if  $\neg M[t\rangle$  then continue
5       $M' := \text{the } \omega\text{-marking such that } M[t\rangle M'$ 
6      if  $M' \in F$  then continue
7      Add- $\omega(M, M')$  // the  $M_0 [t_1 \cdots t\rangle M' > M_0$  test
8      if  $\omega$  was added then if  $M' \in F$  then continue
9      Cover-check( $M'$ ) // only keep maximal — may update  $A$  and  $W$ 
10     if  $M'$  is covered then continue
11      $F := F \cup \{M'\}; A := A \cup \{M'\}; W := W \cup (\{M'\} \times T); M'.B := M$ 
```

F is a hash table of all constructed ω -markings

- unnecessary for correctness, speeds up the algorithm, cheap

A is all kept ω -markings — expensive, touch as little as you can

W is pending work, simpler than it seems, we come back

Simple and natural — how can this beat others?

4 Addition of ω -symbols

Rule of thumb: the earlier they are added, the better for speed

Traditional: scan linear history backwards (the *M.B*)

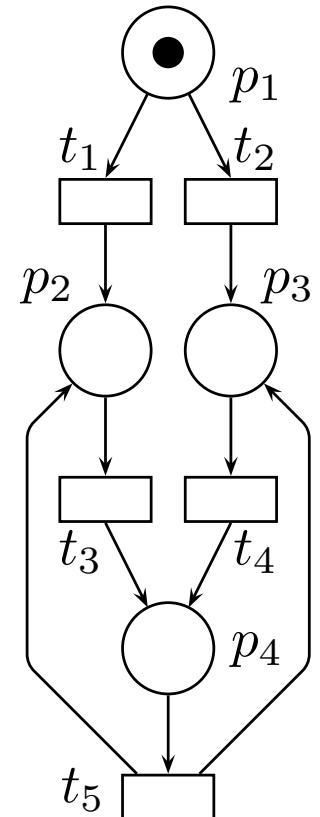
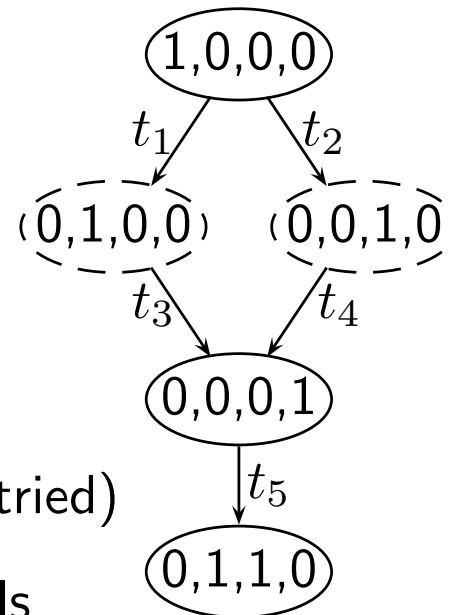
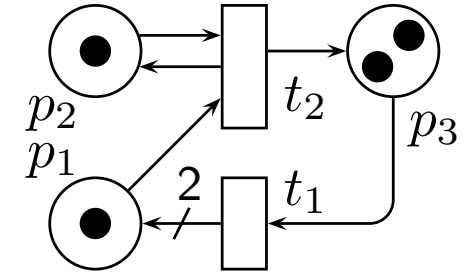
Repeated scanning of history

- $(1, 1, 2) [t_1] (3, 1, 1) [t_2] (2, 1, 2)$
- $(3, 1, 1)$ does not trigger ω -addition to $(2, 1, 2)$
- $(1, 1, 2)$ triggers: $(2, 1, 2) \rightsquigarrow (\omega, 1, 2)$
- history is now fully scanned, but now $(3, 1, 1)$ triggers $(\omega, 1, 2) \rightsquigarrow (\omega, 1, \omega)$
- cheap enough to be always used

History merging

- both $(0, 1, 0, 0)$ and $(0, 0, 1, 0)$ trigger ω -addition in $(0, 1, 1, 0)$
- history becomes a DAG \Rightarrow expensive
- was not strong in our experiments
- ω in kept may match finite in other (not tried)

Let $M \xrightarrow{t} M'$ mean $M [t]$ and add ω -symbols



5 Correctness

Lemma After termination, all reachable markings are covered.

- invariant: for every $M \in F$, there is $M' \in A$ such that $M \leq M'$
- this issue is hard with some competing algorithms

Lemma Every element of A is a limit of reachable markings.

- \hat{M} is trivially a limit
- given limits, operations of the algorithm yield limits
- this lemma justifies non-standard addition of ω -symbols, like history merging

Lemma A only contains maximal ω -markings.

- taken care of explicitly

Lemma The algorithm terminates.

- to avoid termination, infinitely many ω -markings must be constructed
- \Rightarrow an infinite sequence of distinct ω -markings, because T is finite
- \Rightarrow an infinite strictly growing subsequence
- \Rightarrow Add- ω triggers repeatedly, adding ω -symbols
- but there can be at most $|P|$ ω -symbols in an ω -marking

6 Construction Order

Necessary to realize: for almost any algorithm there is a “cheating” easy input

- a transition that adds tokens to every place leads to immediate termination
- an otherwise bad algorithm may hit it much earlier than competing algorithms

Breadth-first

- simple and fast W : queue of ω -markings, scan all transitions in a **for**-loop
- bad in experiments (big $|F|$)

Depth-first

- simple and fast W : a stack of ω -markings, and a transition number in each
- **Lemma** If $M \xrightarrow{t} M'$ adds an ω -symbol, the algorithm will not backtrack from M' before it has investigated all its descendants.

Most tokens first

- let “ \prec ” sort first by the number of ω -symbols, then by the number of tokens
- try ω -markings in that order
- W is a heap of ω -markings with transition numbers, $O(\log |W|)$ operations
- intuitively promising and good in measurements

7 Pruning 1/2

Idea: when removing M_0 from A , also remove (part of) its constructed future

- applied in some competing algorithms
- motivation: if $M > M_0 \xrightarrow{t_1 \dots t_n} M_n$, then M_n would be removed eventually anyway, *if no $\xrightarrow{t_i}$ added ω -symbols*

\Rightarrow improved speed?

Even if the green assumption holds, total pruning of pumping cycles postpones ω -addition

- $(1, 0, 0) \xrightarrow{t_2} (0, 1, 0) \xrightarrow{t_3} (1, 0, \omega) \xrightarrow{t_1} (0, \omega, \omega) \xrightarrow{t_3} (\omega, \omega, \omega)$
- $(1, 0, 0) \xrightarrow{t_2} (0, 1, 0) \xrightarrow{t_3} (1, 0, \omega) \xrightarrow{t_1} (0, 2, \omega) \xrightarrow{t_3} (1, \omega, \omega) \xrightarrow{t_3} (\omega, \omega, \omega)$

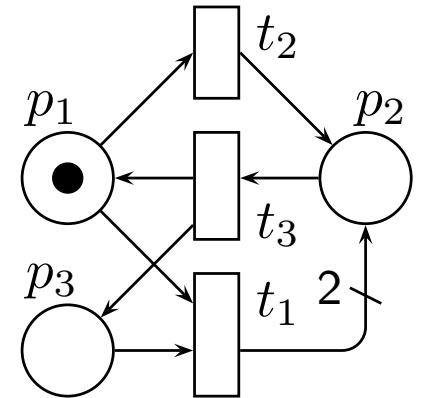
Keeping all constructed in F costs little, and protects against re-constructing

- if $M [t_1 t_2] M_{12}$ and $M [t_2 t_1] M_{21}$, then $M_{21} = M_{12}$

\Rightarrow re-constructing would be common

[ReySer] does not totally prune, and cover-checks against F instead of A

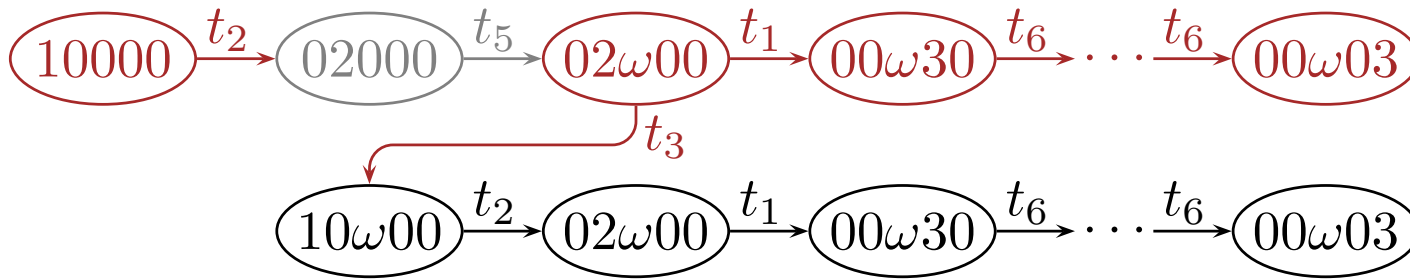
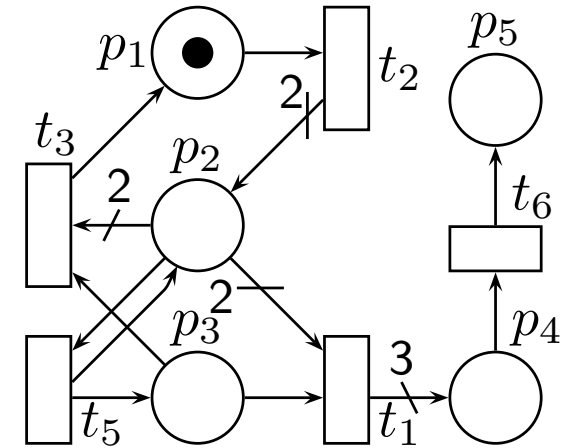
- bad for speed, because F is much bigger and cover-checking is expensive



7 Pruning 2/2

Example violating the green assumption

- most tokens first
- transitions t_1 first, then t_2 , then ...
- pruning algorithm:



⇒ lots of re-activation or re-construction

⇒ I do not believe that pruning is a good idea in this context

8 Good News

Overeager pruning

- assume $M_0 \xrightarrow{t_1 \cdots t_n} M_n$ has been constructed and $M'_0 > M_0$ just been found
- we say that pruning M_n is *overeager*, if $M'_0 [t_1 \cdots t_n \rangle M_n$
- it is possible, if $\xrightarrow{t_1 \cdots t_n}$ adds ω -symbols

Theorem and **Theorem** With depth-first and most tokens first, if history merging is applied, then the effect of non-overeager pruning occurs automatically.

- that is, if pruning would not be overeager, the algorithm will not any more fire transitions from M_n (and if it would, there is no reason to not fire)
- “any more”, because it may have fired many of them before finding M'_0
- proofs are not simple enough for the time that remains (enjoy the paper)
- does not give all possible pruning, but still gives a lot
- (also remember that almost any algorithm has a “cheating” winning example)

So theory suggests that depth-first and most tokens first be better than [ReySer]

- do measurements support this?

9 Measurements

| model | $ A $ | most tokens f. | | depth-first | | breadth-first | | [ReySer] |
|------------|-------|----------------|-------|-------------|-------|---------------|------|----------|
| fms | 24 | 63 | 53 | 110 | 56 | 421 | 139 | 809 |
| kanban | 1 | 12 | 12 | 12 | 12 | 12 | 12 | 114 |
| mesh2x2 | 256 | 479 | 465 | 774 | 455 | 10733 | 2977 | 6241 |
| mesh3x2 | 6400 | 11495 | 11485 | 8573 | 10394 | | | |
| multipoll | 220 | 245 | 234 | 244 | 244 | 507 | 507 | 2004 |
| pncsacover | 80 | 215 | 246 | 284 | 325 | 7122 | 5804 | 1604 |

- $|A|$: final number of ω -markings in the coverability set
- other numbers: total numbers of constructed distinct ω -markings
- transitions tried in two orders (numeric and reverse)
- running times cannot be compared to [ReySer]
- ours < 0.1 s except mesh3x2 and some breadth-first, all ≤ 30 s

Observations

- transition order may have dramatic impact (winning “cheating” already here!)
- \Rightarrow I wish reviewers in general would be less measurement-oriented
- is most tokens first the best, see the largest case?
 - we did not lose

10 Discussion

It seems that with this problem, a simple algorithm wins complicated ones

However, ours was not the most trivial possible

- hash table for F
- repeated scanning of history (cheap enough to be always on)
- history merging (although it had little effect in measurements)
- some thought given to data structures and other details

Construction order is important both at the overall and transition scanning level

- do not believe too much in measurements, in this paper or elsewhere, unless there is a huge meticulously chosen amount of them
- we hope to make some more measurements with bigger nets in the future

THANK YOU FOR ATTENTION!