

# Injectivity of geodesic X-ray transform

$(M, g)$  compact non-trapping Riemannian manifold w/  $\partial M$ .

$f \in \mathcal{I}^b(T^*M \otimes \mathbb{R}^m)$ , symmetric:  
 $=: \mathcal{S}_m(M)$ . For  $\gamma: [a, b] \rightarrow M$  geodesic between boundary pts,  
 $IF(\gamma) = \int_a^b f_{i_1 \dots i_m}(\gamma(t)) \dot{\gamma}^{i_1}(t) \dots \dot{\gamma}^{i_m}(t) dt = \int_a^b \langle f, j_\gamma^m(t) \rangle dt$

Define:  $d: \mathcal{S}_m(M) \rightarrow \mathcal{S}_{m+1}(M)$ ;  $d = \underset{\substack{\uparrow \\ \text{symmetrization}}}{\sigma} \nabla$  ↖ covariant derivative

$\mathcal{P}_m(M) := \{ f \in \mathcal{S}_m(M) \mid f = d\rho \text{ for some } \rho \in \mathcal{S}_{m-1}(M) \text{ w/ } \rho|_{\partial M} = 0 \}$   
 $\mathcal{Z}_m(M) := \{ f \in \mathcal{S}_m(M) \mid \int_a^b \langle f, j_\gamma^m(t) \rangle dt = 0 \forall \gamma \}$

Note:  $\frac{d}{dt} \langle \rho, j_\gamma^m \rangle = \frac{\partial \rho_{i_1 \dots i_m}}{\partial x^j}(\gamma(t)) \dot{\gamma}^j(t) \dot{\gamma}^{i_1}(t) \dots \dot{\gamma}^{i_m}(t) + \sum_{k=1}^m \rho_{i_1 \dots i_{k-1} i_{k+1} \dots i_m}(\gamma(t)) \dot{\gamma}^{i_1}(t) \dots \dot{\gamma}^{i_{k-1}}(t) \dot{\gamma}^{i_{k+1}}(t) \dots \dot{\gamma}^{i_m}(t)$   
 $= \frac{\partial \rho_{i_1 \dots i_m}}{\partial x^j} \dot{\gamma}^j \dot{\gamma}^{i_1} \dots \dot{\gamma}^{i_m} - \sum_{k=1}^m \rho_{i_1 \dots i_{k-1} i_{k+1} \dots i_m} \dot{\gamma}^{i_1} \dots \dot{\gamma}^{i_{k-1}} \dot{\gamma}^{i_{k+1}} \dots \dot{\gamma}^{i_m}$   
 $= \left( \frac{\partial \rho_{i_1 \dots i_m}}{\partial x^j} - \sum_{k=1}^m \Gamma_{j i_1 \dots i_{k-1} i_{k+1} \dots i_m} \right) \dot{\gamma}^{i_1} \dots \dot{\gamma}^{i_m} \dot{\gamma}^j = \langle d\rho, j_\gamma^{m+1} \rangle$   
 $\Rightarrow \int_a^b \langle d\rho, j_\gamma^{m+1} \rangle dt = \langle \rho, j_\gamma^m \rangle \Big|_a^b = 0 = (\sigma \nabla \rho)_{i_1 \dots i_m} \dot{\gamma}^{i_1} \dots \dot{\gamma}^{i_m} \Rightarrow \boxed{\mathcal{P}_m(M) \subset \mathcal{Z}_m(M)}$

Q: For which  $(M, g)$  we have  $\mathcal{Z}_m(M) = \mathcal{P}_m(M)$ ?

Note: For  $m=2$  this is the deformation boundary rigidity problem i.e. the linearization of the boundary rigidity problem

Note: For  $m=0$  this reduces to wave simpler form:

For which  $(M, g)$  we have  $\int_a^b f(\gamma(t)) dt = 0 \forall \gamma \Rightarrow f = 0$ ?

Terminology: If there exists a vector field  $X \neq 0$  along a geodesic  $\gamma: [a, b] \rightarrow M$  s.t.

$D_{\dot{\gamma}} D_{\dot{\gamma}} X + \mathcal{R}(\dot{\gamma}, X)\dot{\gamma} = 0$ ,  $X(a) = 0, X(b) = 0$ ,  
 $\uparrow$  Riemannian curvature tensor

then  $\gamma(a) \in \gamma(b)$  are s-conjugate along  $\gamma$ .

Theorem 1.1 [Dairbekov 06: "Integral geometry problem for non-trapping manifolds" IP 22(2006) 431-445]

Let  $m \geq 1, n \geq 2$ . If  $(M, g)$  has no s-conjugate points for

$s = \frac{m(m+1)}{n+2m-1}$ , then  $\mathcal{Z}_m(M) = \mathcal{P}_m(M)$

Theorem 1.3 [Dairbolar 06] Let  $(M, g)$  be compact non-trapping Riemannian manifold without conjugate points and let  $f \in C^\infty(M)$ ,  
 $\int_{\gamma} f(y) := \int_a^b f(\gamma(t)) dt = 0$  for all geodesics  $\gamma: [a, b] \rightarrow M$   
 between boundary points, then  $f = 0$ .

Pf. Step 1: (Reduction to the Lichnerowicz equation)

Lemma 2.1: If  $\int_{\gamma} f(y) = 0$  for all  $\gamma$ , then  $f|_{\partial M} = 0$ .

Corollary 1: Zero-extension of  $f$  into the diff-top. double  $N$  of  $M$  belongs to  $H^1(N) \cap C(N)$ .

Define  $u: SM \rightarrow \mathbb{R}$ ;  $u(\beta) = \int_{\beta} f(y(t)) dt$ , independent of  $\beta$  s.t.  $\beta|_{\mathbb{R}} \in N \setminus M$

$$K := \{ \beta \in SN \mid \exists_{\mu}^+(\beta) \in SM \text{ for some } t \in \mathbb{R} \} = \text{pr}_{SM} \left( (\mathcal{D}_H)^{-1}(SM) \right)$$

Clearly  $K \subset SN$  is closed and of measure zero. codim 2 in  $\mathbb{R} \times SM$

Lemma 2.3: (i)  $u|_{SM \setminus K} = 0$

(ii)  $u \in H^1(SN \setminus K) \cap C^\infty(SM \setminus K)$

(iii)  $H_u = f$

Pestov's identity

$\pi: TN \rightarrow N$  natural projection,  $\pi^*TN \xrightarrow{q} TN$  pullback bundle

$$\begin{array}{ccc} \text{fiberwise } \rightarrow q & & \\ \text{restriction} & \downarrow & \downarrow \pi \\ & TN & \rightarrow N \end{array}$$

Sections  $\mathcal{F} \in \Gamma(\pi^*TN)$  are smooth vector fields

Idea: Tangent space  $T_x M$  is glued to each  $\beta \in TM$

$$\mathcal{F} = \mathcal{F}^i(x, \beta) e_i|_{(x, \beta)}, \quad q(e_i|_{(x, \beta)}) = \frac{\partial}{\partial x^i}|_x$$

Base manifold has dimension  $2n$ , each fiber has dimension  $n$ .

Define:  $\frac{\partial}{\partial x^i}|_{\beta} \in T_{\beta} TN$  by  $\frac{\partial}{\partial x^i}|_{\beta} := \frac{\partial}{\partial x^i}|_{\beta} - \beta^j \sum_{ij} \frac{\partial}{\partial \beta^j} e_i|_{\beta}$

$$H_{\beta} TN := \text{span} \left\{ \frac{\partial}{\partial x^1}|_{\beta}, \dots, \frac{\partial}{\partial x^n}|_{\beta} \right\}, \quad V_{\beta} TN := \text{span} \left\{ \frac{\partial}{\partial \beta^1}|_{\beta}, \dots, \frac{\partial}{\partial \beta^n}|_{\beta} \right\}$$

$$e_i|_{\beta} \hat{=} \frac{\partial}{\partial x^i}|_{\beta} \hat{=} \frac{\partial}{\partial \beta^i}|_{\beta} \hat{=} \frac{\partial}{\partial x^i}|_x, \quad \pi(\beta) = x$$

$$\pi^*TN|_{\beta} \hat{=} H_{\beta} TN \hat{=} V_{\beta} TN \hat{=} T_x N$$

Horizontal gradient  $\overset{h}{\nabla} u = g^{ij} \frac{\partial u}{\partial x^i} e_j$  for  $u \in C^\infty(TN)$

Vertical gradient  $\overset{v}{\nabla} u = g^{ij} \frac{\partial u}{\partial p^i} e_j$  - " -

Horizontal divergence  $\overset{h}{\text{div}} \bar{\Sigma} = \frac{\partial \bar{\Sigma}^i}{\partial x^i} + \Gamma_{ij}^k \bar{\Sigma}^j$  for  $\bar{\Sigma} \in \Gamma(\pi^*TN)$

Vertical divergence  $\overset{v}{\text{div}} \bar{\Sigma} = \frac{\partial \bar{\Sigma}^i}{\partial p^i}$  - " -

Inherited inner product:  $\langle \bar{\Sigma}, \bar{\Sigma} \rangle = g_{ij} \bar{\Sigma}^i \bar{\Sigma}^j$  - " - ( $\Rightarrow Hu = \langle \bar{\Sigma}, \overset{h}{\nabla} u \rangle$ )

Poincaré's identity:  $2 \langle \overset{h}{\nabla} u, \overset{v}{\nabla}(Hu) \rangle = |\overset{h}{\nabla} u|^2 + \overset{h}{\text{div}} V + \overset{v}{\text{div}} W - \langle \mathcal{R}(\bar{\Sigma}, \overset{v}{\nabla} u) \bar{\Sigma}, \overset{v}{\nabla} u \rangle$

$V = \langle \overset{h}{\nabla} u, \overset{v}{\nabla} u \rangle \bar{\Sigma} - \langle \overset{h}{\nabla} u, \bar{\Sigma} \rangle \overset{v}{\nabla} u$ ,  $W = \langle \overset{h}{\nabla} u, \bar{\Sigma} \rangle \overset{h}{\nabla} u$

Gauss-Ostrogradsky formula: Let  $\bar{\Sigma} \in \Gamma(\pi^*TN)$  be  $r$ -homogeneous. Then

$$\int_{SM} \overset{h}{\text{div}} \bar{\Sigma} d\mathcal{P} dx = (-1)^n \int_{\partial SM} \langle \bar{\Sigma}, \bar{\nu} \rangle d\mathcal{P} dx, \quad \int_{SM} \overset{v}{\text{div}} \bar{\Sigma} d\mathcal{P} dx = (r+n-1) \int_{SM} \langle \bar{\Sigma}, \bar{\Sigma} \rangle d\mathcal{P} dx.$$

Since  $u(\lambda \bar{\Sigma}) = \int_{\lambda \mathcal{P}} f(y_{\lambda \mathcal{P}}(t)) dt = \frac{1}{\lambda} \int_{\mathcal{P}} f(y_{\mathcal{P}}(\lambda t)) \lambda dt = \frac{1}{\lambda} \int_{\mathcal{P}} f(y_{\mathcal{P}}(s)) ds = \frac{1}{\lambda} u(\bar{\Sigma})$



$$\int_{SD} (|\overset{h}{\nabla} u|^2 - \langle \mathcal{R}(\bar{\Sigma}, \overset{v}{\nabla} u) \bar{\Sigma}, \overset{v}{\nabla} u \rangle) d\mathcal{P} dx + (-1)^n \int_{\partial SD} \langle \bar{\Sigma}, \bar{\nu} \rangle d\mathcal{P} dx + (n-2) \int_{SD} \langle \bar{\Sigma}, W \rangle d\mathcal{P} dx = 0$$

$u|_{S^{n-1}} = 0$   
 $(Hu)^2 = f^2$

Define  $\overset{h}{\nabla}'' u = \overset{h}{\nabla} u - \langle \overset{h}{\nabla} u, \bar{\Sigma} \rangle \bar{\Sigma}$  on  $\partial SD$ . Then

$$\langle \bar{\Sigma}, V \rangle = \langle \overset{h}{\nabla}'' u, \overset{v}{\nabla} u \rangle \langle \bar{\Sigma}, \bar{\Sigma} \rangle - \langle \overset{h}{\nabla}'' u, \bar{\Sigma} \rangle \langle \overset{v}{\nabla} u, \bar{\Sigma} \rangle = 0.$$

$u|_{\partial SD} = 0$

Lemma 5.1 Let  $u: SD \rightarrow \mathbb{R}$  be such that  $u \in H^1(SD)$ ,  $u|_{\partial SM} = 0$ ,  $Hu = f$ . Then

Lemma 5.1:

Then  $\int_{SM} (|\overset{h}{\nabla} u|^2 - \langle \mathcal{R}(\bar{\Sigma}, \overset{v}{\nabla} u) \bar{\Sigma}, \overset{v}{\nabla} u \rangle) d\mathcal{P} dx = -(n-2) \int_{SM} f^2 d\mathcal{P} dx.$

Define  $\overset{v}{\nabla}'' u = \overset{v}{\nabla} u - \langle \overset{v}{\nabla} u, \bar{\Sigma} \rangle \bar{\Sigma}$ . (The  $\overset{v}{\nabla}'' u$  depends only on  $u|_{SM}$ )

Now  $D_{\bar{\Sigma}}(\overset{v}{\nabla} u) = \langle \bar{\Sigma}, \overset{h}{\nabla} \overset{v}{\nabla} u \rangle = \overset{v}{\nabla}(Hu) - \overset{h}{\nabla} u = -\overset{h}{\nabla} u$ ,  $\langle \bar{\Sigma}, \overset{v}{\nabla} u \rangle = -u$  (by homogeneity)

$\Rightarrow D_{\bar{\Sigma}}(\overset{v}{\nabla}'' u) = -\overset{h}{\nabla} u + D_{\bar{\Sigma}}(u \bar{\Sigma}) = -\overset{h}{\nabla} u + f \bar{\Sigma}$

$\Rightarrow |D_{\bar{\Sigma}}(\overset{v}{\nabla}'' u)|^2 = |\overset{h}{\nabla} u|^2 + f^2 - 2f \langle \bar{\Sigma}, \overset{v}{\nabla} u \rangle = |\overset{h}{\nabla} u|^2 - f^2$   
 $= Hu = f$

$\Rightarrow \int_{SM} (|D_{\bar{\Sigma}}(\overset{v}{\nabla}'' u)|^2 - \langle \overset{v}{\nabla}'' u, \mathcal{R}(\bar{\Sigma}, \overset{v}{\nabla}'' u) \bar{\Sigma} \rangle) d\mathcal{P} dx = -(n-1) \int_{SM} f^2 d\mathcal{P} dx$

$\int_{\partial SM} \left( \int_0^{\Sigma_2(\eta)} (|D_{\bar{\Sigma}} \Sigma|^2 - \langle \Sigma, \mathcal{R}(\bar{\Sigma}, \Sigma) \bar{\Sigma} \rangle) dt \right) g(\eta, \eta) d\eta d\eta$ ,  $\Sigma_\eta(t) = \overset{v}{\nabla}'' u(j_\eta(t))$

Index form  $I(\Sigma, \Sigma) > 0$  for nonzero  $\Sigma(t)$  with  $\Sigma(a) = \Sigma(b) = 0$   
 $\Leftrightarrow$  no conjugate points along  $j_\eta: [a, b] \rightarrow M$   $\square$