

# The covariant derivative and the geodesic flow

M. Dahl

## Directional derivative for a scalar function

Suppose  $y \in T_p M$  and  $f \in C^\infty(M)$ . Let

$$y(f) := (f \circ c)'(0)$$

where  $c: I \rightarrow M$  is a curve that represents  $y$ ;  $c(0) = p$ ,  $\dot{c}(0) = y$ .

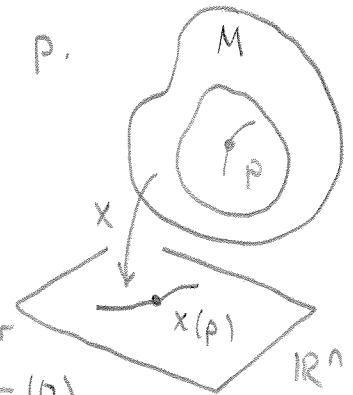
Interpretation:  $y(f)$  describes how much  $f$  is changing in the direction of  $y$ .

Let us express  $y(f)$  in local coords.

Let  $x^i$  be local coordinates around  $p$ .

$$(f \circ c)'(0) = \left( \underbrace{(f \circ x^{-1})}_{\mathbb{R}^n \rightarrow \mathbb{R}} \circ \underbrace{(x \circ c)}_{I \rightarrow \mathbb{R}^n} \right)'(0)$$

$$= \frac{\partial (f \circ x^{-1})}{\partial x^r} \underbrace{(x \circ c(0))}_{= x(p)} \cdot \frac{d(x \circ c)^r}{dt}(0)$$



$$\left[ \text{If } c: I \rightarrow M, \text{ then } \dot{c}: I \rightarrow TM \text{ is defined as} \right. \\ \dot{c}(t) = \underbrace{\frac{dc^i}{dt}(t)}_{= \frac{d(x \circ c)^i}{dt}(t)} \frac{\partial}{\partial x^i} \Big|_{c(t)} \Rightarrow \frac{d(x \circ c)^r}{dt}(0) \\ \left. y(f) = \frac{\partial (f \circ x^{-1})}{\partial x^r} (x(p)) y^r = y^r \right.$$

## Remarks

a) If  $f \in C^\infty(M)$ , and  $x^i$  are local coords around  $p$ ,

$$\begin{aligned} \frac{\partial f}{\partial x^i}(p) &:= \left. \frac{\partial}{\partial x^i} \right|_p (f) \quad \text{let} \\ &= \frac{\partial (f \circ x^{-1})}{\partial x^i}(x(p)) \end{aligned}$$


b)  $v(fg) = v(f) \cdot g + f v(g)$

c)  $\frac{\partial^2 f}{\partial x^i \partial x^j}(p) := \left( \frac{\partial}{\partial x^i} \frac{\partial f}{\partial x^j} \right)(p) = \frac{\partial^2 (f \circ x^{-1})}{\partial x^i \partial x^j}(x(p))$

## Vector fields

$\mathfrak{X}(M)$  = set of smooth maps  $X: M \rightarrow TM$   
such that  $X_p \in T_p M$ ,  $p \in M$

Locally  $X \in \mathfrak{X}(M)$  can be written as  $X = X^i \frac{\partial}{\partial x^i}$  where  $X^i \in C^\infty(M)$ .



If  $f \in C^\infty(M)$  and  $X \in \mathfrak{X}(M)$ , then  $X(f) \in C^\infty(M)$  is defined pointwise:

$$X(f)|_p = X_p(f) = X^i(p) \frac{\partial f}{\partial x^i}(p)$$

so

$$X(f) = X^i \frac{\partial f}{\partial x^i}$$

## Lie bracket for vector fields

Def. Let  $X, Y \in \mathfrak{X}(M)$ . Then  $[X, Y] \in \mathfrak{X}(M)$  is the unique v. field such that

$$[X, Y](f) = X(Y(f)) - Y(X(f)) \quad \forall f \in C^\infty(M)$$

(x)

Proof.

$$\text{RHS} = X(Y(f)) - Y(X(f))$$

$$= X\left(\gamma^i \frac{\partial f}{\partial x^i}\right) - Y\left(\chi^i \frac{\partial f}{\partial x^i}\right)$$

$$= X^j \frac{\partial \gamma^i}{\partial x^j} \frac{\partial f}{\partial x^i} + X^j \gamma^i \frac{\partial^2 f}{\partial x^j \partial x^i} - \gamma^j \frac{\partial \chi^i}{\partial x^j} \frac{\partial f}{\partial x^i} - \gamma^j \chi^i \frac{\partial^2 f}{\partial x^i \partial x^j}$$

$$= \underbrace{\left( X^j \frac{\partial \gamma^i}{\partial x^j} - \gamma^j \frac{\partial \chi^i}{\partial x^j} \right)}_{=: Z \in \mathfrak{X}(U)} \frac{\partial}{\partial x^i} (f)$$

$\Rightarrow Z \in \mathfrak{X}(U)$ ,  $U \subset M$  chart where  $x^i$  are defined.

$\Rightarrow$  In each chart there is a v.f.  $Z$  satisfying (\*).

Suppose  $\tilde{Z} \in \mathfrak{X}(U)$  also satisfies (\*)

$$\Rightarrow Z(f) = \tilde{Z}(f) \quad \forall f \in C^\infty(M)$$

$$\Rightarrow Z = \tilde{Z}$$

$\Rightarrow$  definition of  $Z$  doesn't depend on  $x^i$

$\Rightarrow \exists Z \in \mathfrak{X}(M)$  satisfying (\*).  $\square$

Remarks: a) In local coordinates:

$$[X, Y]_p = \left( \frac{\partial \gamma^i}{\partial x^j} \chi^j - \gamma^j \frac{\partial \chi^i}{\partial x^j} \right)_p \frac{\partial}{\partial x^i} \Big|_p$$

$$b) [X, Y] = -[Y, X]$$

$$c) \left[ \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^k} \right] = 0$$

d)  $[\cdot, \cdot]$  is canonical; it doesn't depend on any additional structure on the manifold.

## Covariant derivative for vector fields.

Next, we describe the Levi-Civita connection. It is a directional derivative for vector fields on a manifold.

Theorem: On a Riemannian manifold there exists a unique map:

$$\begin{aligned} \nabla: \mathfrak{X}(M) \times \mathfrak{X}(M) &\longrightarrow \mathfrak{X}(M) \\ (X, Y) &\longmapsto \nabla_X Y \end{aligned}$$

characterized by conditions:

a)  $\nabla_X Y$  is  $\mathbb{R}$ -linear in  $Y$

$\nabla_X Y$  is  $C^\infty(M)$ -linear in  $X$

b)  $\nabla_X (fY) = X(f)Y + f \nabla_X Y$ ,  $f \in C^\infty(M)$ ,  $X, Y \in \mathfrak{X}(M)$

c) If  $X, Y \in \mathfrak{X}(M)$ , then

$$\nabla_X Y - \nabla_Y X = [X, Y]$$

d) If  $X, Y, Z \in \mathfrak{X}(M)$ , then

$$X(g(Y, Z)) = g(\nabla_X Y, Z) + g(Y, \nabla_X Z).$$

Proof. We first derive an implicit eqn. for  $\nabla_X Y$ . This will prove uniqueness. From this eqn, we then derive an explicit expression for  $\nabla$  and this will imply existence.

For uniqueness, let us assume that  $\nabla$  exists and  $\nabla$  satisfies conditions a-d.

Let  $X, Y, Z \in \mathfrak{X}(M)$ . Then:

$$\begin{aligned} X(g(Y, Z)) &= g(\nabla_X Y, Z) + g(Y, \nabla_X Z) \\ Y(g(X, Z)) &= g(\nabla_Y X, Z) + g(X, \nabla_Y Z) \\ \underline{Z(g(X, Y))} &= \underline{g(\nabla_Z X, Y)} - g(X, \nabla_Z Y) \end{aligned}$$

$$\begin{aligned} X(g(Y, Z)) + Y(g(X, Z)) - Z(g(X, Y)) &= g(\underbrace{\nabla_X Y + \nabla_Y X}_{\square}, Z) + g(Y, \underbrace{\nabla_X Z - \nabla_Z X}_{\sim}) + g(X, \underbrace{\nabla_Y Z - \nabla_Z Y}_0) \\ &= \nabla_Y X + [X, Y] + \nabla_Y X = [X, Z] = [Y, Z] \\ &= 2g(\nabla_Y X, Z) + g(Z, [X, Y]) + g(Y, [X, Z]) + g(X, [Y, Z]) \end{aligned}$$

Solving for  $2g(\nabla_Y X, Z)$  yields Kozul's formula:

$$\begin{aligned} 2g(\nabla_Y X, Z) &= X(g(Y, Z)) + Y(g(X, Z)) - Z(g(X, Y)) \\ &\quad - g(Z, [X, Y]) - g(Y, [X, Z]) - g(X, [Y, Z]) \end{aligned}$$

$\forall X, Y, Z \in \mathfrak{X}(M)$ .

The RHS depends only on the metric. This is the implicit eqn. for  $\nabla$ .

Claim: The Kozul formula determines  $\nabla_Y X$ ,  $X, Y \in \mathfrak{X}(M)$

Proof. We wish to prove:

The Kozul formula determines:  $2g((\nabla_Y X)_p, u)$ ,  $u \in T_p M$

Let  $Z \in \mathfrak{X}(M)$  be an extension of  $u$   $Z_p = u$ . Then  
(we shortly prove existence...)

$$2g((\nabla_Y X)_p, u_p) = 2g(\nabla_Y X, Z)|_p = \text{RHS}|_p$$

By inspecting the RHS in Kozul's formula, it may depend on

$$Z^k(p) = u^k \quad \text{and} \quad \frac{\partial Z^k}{\partial x^r}(p).$$

However, as the LHS does not depend on  $\frac{\partial Z^k}{\partial x^r}(p)$ , the RHS can neither.

$\Rightarrow$  RHS doesn't depend on the extension of  $u$

$\Rightarrow$  we may solve  $(\nabla_Y X)_p$  from Kozul's formula

$\Rightarrow \nabla_Y X$  is uniquely determined by  $a, b, c, d$ .  $\square$

Existence: We start with a formal calculation where we derive an explicit expression for  $\nabla_Y X$  from Kozul's formula.

Let  $X = \frac{\partial}{\partial x^i}$ ,  $Y = \frac{\partial}{\partial x^j}$ ,  $Z = \frac{\partial}{\partial x^k}$ ,  $u = \frac{\partial}{\partial x^l}$

$$\Rightarrow 2g\left(\nabla_{\frac{\partial}{\partial x^j}} \frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^k}\right) =$$

$$\frac{\partial g_{jk}}{\partial x^i} + \frac{\partial g_{ik}}{\partial x^j} - \frac{\partial g_{ij}}{\partial x^k}$$

$$\Rightarrow g_{ak} \left(\nabla_{\frac{\partial}{\partial x^j}} \frac{\partial}{\partial x^i}\right)^a = \frac{1}{2} \left( \frac{\partial g_{jk}}{\partial x^i} + \frac{\partial g_{ik}}{\partial x^j} - \frac{\partial g_{ij}}{\partial x^k} \right) | g^{bk}$$

$$\Rightarrow \left(\nabla_{\frac{\partial}{\partial x^j}} \frac{\partial}{\partial x^i}\right)^b = \frac{1}{2} g^{kb} \left( \frac{\partial g_{jk}}{\partial x^i} + \frac{\partial g_{ik}}{\partial x^j} - \frac{\partial g_{ij}}{\partial x^k} \right)$$

$$= \Gamma_{ij}^b$$

$$\Rightarrow \nabla_{\frac{\partial}{\partial x^j}} \left(\frac{\partial}{\partial x^i}\right) = \Gamma_{ij}^b \frac{\partial}{\partial x^b}$$

$$\begin{aligned}
 \underline{\nabla_X Y} &= \nabla_{X^j \frac{\partial}{\partial x^j}} Y^i \frac{\partial}{\partial x^i} \\
 &= X^j \nabla_{\frac{\partial}{\partial x^j}} \left( Y^i \frac{\partial}{\partial x^i} \right) \\
 &= X^j \left( \frac{\partial Y^a}{\partial x^j} \frac{\partial}{\partial x^a} + Y^i \underbrace{\nabla_{\frac{\partial}{\partial x^j}} \frac{\partial}{\partial x^i}} \right) \\
 &= X^j \left( \frac{\partial Y^a}{\partial x^j} + \Gamma_{ij}^a Y^i \right) \frac{\partial}{\partial x^a} = \Gamma_{ij}^a \frac{\partial}{\partial x^a} \quad (*)
 \end{aligned}$$


---

In local coordinates, we define  $\nabla$  by (\*).

Now  $\nabla$  satisfies conditions a-d:

a)  $\mathbb{R}$ -linear in  $Y$   $\Rightarrow \nabla$  is unique  
 $C^\infty(M)$ -linear in  $X$   $\Rightarrow \nabla$  does not depend on local coordinates.

$$\begin{aligned}
 \text{b) } \nabla_X (fY) &= X^j \left( \frac{\partial (fY^a)}{\partial x^j} + \Gamma_{ij}^a (fY^i) \right) \frac{\partial}{\partial x^a} \\
 &= \left( X^j \frac{\partial f}{\partial x^j} Y^a + X^j f \frac{\partial Y^a}{\partial x^j} + X^j \Gamma_{ij}^a f Y^i \right) \frac{\partial}{\partial x^a} \\
 &= X(f) \cdot Y + f \nabla_X Y
 \end{aligned}$$

$$\text{c) } \nabla_X Y = X^j \left( \frac{\partial Y^a}{\partial x^j} + \Gamma_{ij}^a Y^i \right) \frac{\partial}{\partial x^a}$$

$$\Sigma \quad - \nabla_Y X = -Y^j \left( \frac{\partial X^a}{\partial x^j} + \Gamma_{ij}^a X^i \right) \frac{\partial}{\partial x^a}$$

$$\begin{aligned}
 \nabla_X Y - \nabla_Y X &= \left( X^j \frac{\partial Y^a}{\partial x^j} - Y^j \frac{\partial X^a}{\partial x^j} \right) \frac{\partial}{\partial x^a} = [X, Y] \\
 &+ \left( X^j Y^i \Gamma_{ij}^a - X^i Y^j \Gamma_{ij}^a \right) \frac{\partial}{\partial x^a} \\
 &= X^i Y^j \left( \Gamma_{ji}^a - \Gamma_{ij}^a \right) \\
 &= 0 \quad ; \quad \Gamma_{ij}^a = \Gamma_{ji}^a
 \end{aligned}$$

$$\begin{aligned}
 d) \quad g(\nabla_x Y, Z) &= g_{ak} X^j \left( \frac{\partial Y^a}{\partial x^j} + \Gamma_{ij}^a Y^i \right) Z^k \\
 &= g_{ak} X^j \frac{\partial Y^a}{\partial x^j} Z^k + \underbrace{g_{ak} X^j \Gamma_{ij}^a Y^i Z^k}_{= \Gamma_{kij} X^j Y^i Z^k}
 \end{aligned}$$

Exchanging  $Y \leftrightarrow Z$

$$\begin{aligned}
 \Rightarrow g(Y, \nabla_x Z) &= g_{ak} X^j \frac{\partial Z^a}{\partial x^j} Y^k + \underbrace{g_{ak} X^j \Gamma_{ij}^a Z^i Y^k}_{= \Gamma_{kij} X^j Z^i Y^k} \\
 &= \Gamma_{kij} X^j Z^i Y^k = \Gamma_{ikj} X^j Z^k Y^i
 \end{aligned}$$

$$\begin{aligned}
 g(\nabla_x Y, Z) + g(Y, \nabla_x Z) &= g_{ak} X^j \left( \frac{\partial Y^a}{\partial x^j} Z^k + Y^a \frac{\partial Z^k}{\partial x^j} \right) + \underbrace{(\Gamma_{kij} + \Gamma_{ikj}) X^j Y^i Z^k}_{\stackrel{(*)}{=} \frac{\partial g_{ik}}{\partial x^j}} \\
 &= \frac{\partial (Y^a Z^k)}{\partial x^j}
 \end{aligned}$$

$$= X^j \left( g_{ak} \frac{\partial (Y^a Z^k)}{\partial x^j} + \frac{\partial g_{ak}}{\partial x^j} Y^a Z^k \right)$$

$$= X^j \frac{\partial}{\partial x^j} (g(Y, Z)) = X(g(Y, Z))$$

(\*)

$$\text{Let } \Gamma_{ijk} := g_{ia} \Gamma_{jk}^a = \frac{1}{2} \left( \frac{\partial g_{ij}}{\partial x^k} + \frac{\partial g_{ik}}{\partial x^j} - \frac{\partial g_{jk}}{\partial x^i} \right)$$

$$\Rightarrow \Gamma_{ijk} = \frac{1}{2} \left( \frac{\partial g_{ji}}{\partial x^k} + \frac{\partial g_{jk}}{\partial x^i} - \frac{\partial g_{ik}}{\partial x^j} \right)$$

$$\Rightarrow \Gamma_{ijk} + \Gamma_{jik} = \frac{\partial g_{ij}}{\partial x^k}$$

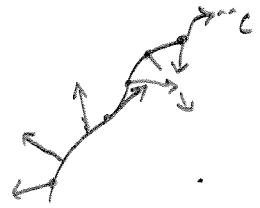
□

Remark 1 a)  $\nabla$  is a map  $T_p M \times \mathbb{F}(M) \rightarrow T_p M : (D_x Y)_p = D_{x_p} Y|_p$

b) If  $\Gamma_{jk}^i = 0$ , then  $\nabla_x Y|_p = X^j \frac{\partial Y^a}{\partial x^j} \frac{\partial}{\partial x^a} \Big|_{t=0} Y(p + tX)$   
in  $\mathbb{R}^n$



# Covariant derivative on a curve



Let  $c: I \rightarrow M$  be a curve.

$$\mathcal{X}(c, M) = \text{maps } X: I \rightarrow TM \text{ s.t. } X_t \in T_{c(t)}M$$

$$= \text{maps } I \rightarrow M$$

(Note:  $\mathcal{X}(c, M)$  is not a vector space)

Examples:  $\dot{c} \in \mathcal{X}(c, M)$

Definition: The covariant der.  $\mathcal{D}_c$  on  $c$  is the map

$$\mathcal{D}_c: I \times \mathcal{X}(c, M) \rightarrow TM$$

$$(t, X) \longmapsto (\mathcal{D}_c X)_t$$

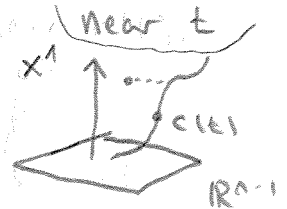
defined by  $(\mathcal{D}_c X)_t = \nabla_{\dot{c}(t)} \tilde{X}$  where  $\tilde{X}$  is an extension of  $X$  near  $c(t)$ .

$$\tilde{X} \in \mathcal{X}(M), \tilde{X}|_c = X \text{ near } t$$

Claim: We can always construct  $\tilde{X}$ .

Proof: We may assume that  $c^1: I \rightarrow \mathbb{R}$  is str. inc. s.c.

Think of  $c^1(t)$  as the "height of  $c(t)$ " near  $t$



Near  $c(t)$  define

$$\tilde{X}(x^1, \dots, x^n) = X(\underbrace{(c^1)^{-1}(x^1)})$$

$$t \text{ s.t. } c^1(t) = x^1$$

We have defined  $\tilde{X}$  near  $c(t)$ . By a suitable cut-off function,  $\tilde{X}$  extends to all  $M$ .  $\square$

Claim:  $D_{\dot{c}} X$  does not depend on  $\tilde{X}$

Proof:

$$\begin{aligned}
 (D_{\dot{c}} X)_t &= (\nabla_{\dot{c}(t)} \tilde{X}) \\
 &= \dot{c}^i(t) \left( \frac{\partial \tilde{X}^a}{\partial x^i} + \Gamma_{ij}^a \tilde{X}^j \right) \frac{\partial}{\partial x^a} \Big|_{c(t)} \\
 &= \left( \dot{c}^i(t) (\tilde{X}^a) + \Gamma_{ij}^a(c(t)) \dot{c}^i X^j \right) \frac{\partial}{\partial x^a} \Big|_{c(t)} \\
 &= \frac{d}{dt} (\tilde{X}^a \circ c) \quad (c \text{ represents } \dot{c}) \\
 &= \frac{dX^a}{dt} \\
 &= \left( \left( \frac{dX^a}{dt} + \Gamma_{ij}^a \circ c \cdot \dot{c}^i X^j \right) (t) \right) \frac{\partial}{\partial x^a} \Big|_{c(t)} \quad \square
 \end{aligned}$$

Properties of  $D_{\dot{c}} X$

a)  $D_{\dot{c}} X$   $\mathbb{R}$ -linear in  $X$

b)  $D_{\dot{c}}(fX) = \frac{df}{dt} X + f D_{\dot{c}} X \quad f \in C^\infty(I)$

c)  $\frac{d}{dt} g(X, Y) = g(D_{\dot{c}} X, Y) + g(X, D_{\dot{c}} Y)$

Proof: For c) we have

$$\text{RHS} = g(\nabla_{\dot{c}(t)} \tilde{X}, \tilde{Y}) + g(\tilde{X}, \nabla_{\dot{c}(t)} \tilde{Y})$$

$$= \dot{c}^i(t) (g(\tilde{X}, \tilde{Y})) = \frac{d}{dt} (g(\tilde{X}, \tilde{Y}) \circ c) = \frac{d}{dt} g(X, Y)$$

$\square$

The next theorem gives a coordinate-free condition for a curve to be a geodesic.

Theorem: Let  $c: I \rightarrow M$  be a curve. Then  $c$  is a geodesic  $\Leftrightarrow D_c \dot{c} = 0$ .

Proof: For a curve  $c$ ,

$$D_c \dot{c} = \frac{d c^i}{dt} + \Gamma_{ab}^i(c(t)) \dot{c}^a \dot{c}^b(t)$$

□