

SGM-manifolds

The following properties of compact (M, g) can be expressed in terms of $d: \partial M \times \partial M \rightarrow \mathbb{R}$ only:

① All geodesic segments strongly minimize:

$$\forall \beta \in \mathcal{B}_{\partial M} = \{\beta \in T\partial M \mid \|\beta\|_g < 1\} \quad \exists! y \in \partial M \text{ s.t.}$$

$$(i) \quad \text{grad}_{\partial M} d(y, \cdot)|_x = \beta, \quad x = \pi(\beta)$$

$$(ii) \quad \exists z \in \partial M \setminus \{x, y\} : d(x, y) = d(x, z) + d(z, y).$$

Assume ①

② $\gamma: [a, b] \rightarrow \partial M$ is a geodesic of M (as well as of ∂M):

$$L(\gamma) = d(x, z), \quad \gamma(a) = x, \quad \gamma(b) = z$$

$\exists \{\beta_i\} \subset \mathcal{B}_x \partial M, \beta_i \rightarrow \beta(a)$ s.t. $\{\gamma_i\}$ determined from ①

converge to $\gamma \in \partial M$ s.t. $d(x, z) + d(z, y) = d(x, y)$

Then we say that γ is a straight segment of ∂M .



③ The length minimizing path $\gamma: [a, b] \rightarrow M$ from x to y is a (possibly grazing) geodesic:

$\{z \in \partial M \mid d(x, z) + d(z, y) = d(x, y)\}$ is a countable union of straight segments and points.

Then we say that x, y are straight connected.

④ There do not exist infinite grazing geodesics:

$\exists \{x_i\} \subset \partial M$ s.t. x_i & x_{i+1} are straight connected,

$$\|\text{grad}_{\partial M} (x_i, \cdot)\|_i = 1, \quad \text{grad}_{\partial M} (x_{i-1}, \cdot)|_i = -\text{grad}_{\partial M} (x_{i+1}, \cdot)|_i$$

$$\text{and } \sum_{i=0}^{\infty} d(x_i, x_{i+1}) = \infty.$$

Definition: (M, g) is SGM, if it satisfies ① & ④.

Lemma: If (M, g) and (\tilde{M}, \tilde{g}) are SGM and $d = \tilde{d}$, then $F = \tilde{F}$, where $F: \partial_{SM} \rightarrow \mathbb{R} \times \partial SM$; $F(p) = (\varepsilon_+(p), \tilde{\sigma}_H^{\varepsilon_+(p)}(p))$.

Proof: $d = \tilde{d} \Rightarrow (\partial M, g|_{\partial M}) = (\partial \tilde{M}, \tilde{g}|_{\partial \tilde{M}})$.

Let $p_0 \in \partial_{SM}$ and $p \in \mathbb{R} \times \partial M$ s.t. $p_0 = p + \sqrt{1 - |p|^2} z_-$.

Let $y \in \partial M$ be determined by ①.

Then y is the first point where the geod. emanating from p_0 hits ∂M , and $\varepsilon_+(p_0) = d(x, y)$, because it must be a length minimizing arc, $\pi(p_0)$.

Now the points y coincide for (M, g) & (\tilde{M}, \tilde{g}) since they are determined by $d = \tilde{d}$ only!

Now there exists a unique $q_0 \in \partial_{SM}$ at y which gives rise to a geodesic which hits ∂M at x .

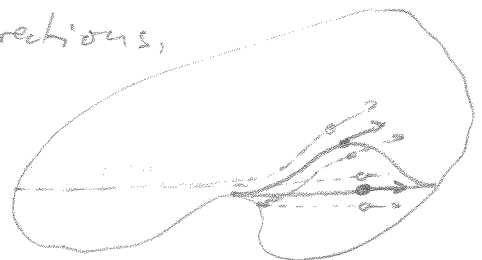
Furthermore $F(p_0) = (d(x, y), q_0)$ and q_0 is determined by $d = \tilde{d}$ only, so $F = \tilde{F}$ \square

Lemma: Let (M, g) and (\tilde{M}, \tilde{g}) be SGM and $d = \tilde{d}$.

Then $G: SM \rightarrow \tilde{SM}$, $G(p) = \tilde{\sigma}_H^{\tilde{\varepsilon}_-(p)} \circ \tilde{\sigma}_H^{-\varepsilon_-(p)}(p)$ is a homeomorphism and $\text{Vol}(M) = \text{Vol}(\tilde{M})$.

Proof: G is diffeo except at tangential directions, where it is local homeo.

$\text{Vol}(M) = \text{Vol}(\tilde{M})$ follows from Santaló - formula



Lemma: If we can show that G covers a map $F: M \rightarrow \tilde{M}$, then F must be an isometry.

Proof: Assume that $\exists p \in \partial_{SM}$: $\begin{cases} x = \tilde{\sigma}_H^+(p) \\ y = \tilde{\sigma}_H^-(p) \end{cases}$. Then $\begin{cases} F(x) = \tilde{\sigma}_H^+(p) \\ F(y) = \tilde{\sigma}_H^-(p) \end{cases}$ and since all geodesics are minimizing,

$$d_M(x, y) = d_{\tilde{M}}(F(x), F(y))$$

Theorem: Let (M, g) be SGM. If $\tilde{g} = \Omega^2 g$ and $\tilde{d}_{SM} = d_{SM}$, then $\Omega = 1$

Proof:

$$|\Omega|^{n-1} \int_M \Omega(x) dx = \int_{SM} (\Omega \circ \pi) \chi(B) d\mathcal{P} = \int_{SM} |\chi|_{\tilde{g}} d\mathcal{P}$$

$$\left[|\chi|_{\tilde{g}} = \sqrt{\tilde{g}(B, B)} = \Omega(\pi(B)) \sqrt{g(B, B)} = (\Omega \circ \pi)(B) \right]$$

$$= \int_{\partial SM} \int_0^{\tilde{r}_H(\gamma)} |\dot{\gamma}_H^+(t)|_{\tilde{g}} dt g(r, \gamma) d\gamma$$

$$= \int_{\partial SM} |\dot{\gamma}(t)|_{\tilde{g}} dt, \text{ where } \gamma(t) = \pi \circ \tilde{\gamma}_H^+(t)$$

$$\left[\begin{array}{l} \text{Since boundary geodesics minimize on } (M, \tilde{g}), \\ \int_0^{\tilde{r}_H(\gamma)} |\dot{\gamma}_H^+(t)|_{\tilde{g}} dt = L(\gamma) \geq \tilde{r}_H(\gamma) \end{array} \right]$$

$$\geq \int_{\partial SM} \tilde{r}_H(\gamma) d\gamma = \int_{SM} d\mathcal{P} = |\Omega|^{n-1} \text{Vol}_g(M)$$

$$\Rightarrow \left| \int_M \Omega(x) dx \geq \text{Vol}_g(M) \right|$$

$$\int_M \Omega(x) dx \leq \left(\int_M \Omega(x)^n dx \right)^{\frac{1}{n}} \left(\int_M dx \right)^{\frac{n-1}{n}} = \text{Vol}_{\tilde{g}}(M)^{\frac{1}{n}} \text{Vol}_g(M)^{\frac{n-1}{n}}$$

$$\Rightarrow \text{Vol}_g(M) \leq \text{Vol}_{\tilde{g}}(M) \text{Vol}_g(M)^{\frac{n-1}{n}} \Rightarrow \text{Vol}_g(M) \leq \text{Vol}_{\tilde{g}}(M)$$

But $g \geq \tilde{g}$ can be interchanged to get eq, and here $\Omega = c = 1$

□

Sasaki-metric on TM

(M, g) Riemannian $\Rightarrow \gamma: [a, b] \rightarrow M$ is a geodesic; \underline{f}

$j: [a, b] \rightarrow TM$ is an integral curve of $H = \frac{1}{2} \frac{\partial^2}{\partial x^i \partial x^i} - \frac{1}{2} \frac{\partial^2}{\partial t^2} - \frac{\partial^2}{\partial x^k \partial x^k}$.

Define $\frac{\partial}{\partial x^i} \Big|_p = \frac{\partial}{\partial x^i} \Big|_p - \frac{1}{2} \frac{\partial^2}{\partial x^k \partial x^k} \Big|_p$. ($\Rightarrow H = \frac{1}{2} \frac{\partial^2}{\partial x^k \partial x^k}$)

Then $\frac{\partial}{\partial x^1} \Big|_p, \dots, \frac{\partial}{\partial x^n} \Big|_p$ form a basis for a subspace $H_p TM \subset T_p TM$

complementary to $V_p TM := \text{Ker}(\pi_* \Big|_p)$, $\pi: TM \rightarrow M$

$$\pi_* \Big|_p: T_p TM \rightarrow T_x M$$

Now $\pi_* \Big|_p: H_p TM \rightarrow T_x M$ is a linear isomorphism as well as

$$\kappa \Big|_p: V_p TM \rightarrow T_x M; \kappa \Big|_p \left(\sum^i \xi^i \frac{\partial}{\partial x^i} \Big|_p + \sum^j \nu^j \frac{\partial}{\partial t} \Big|_p \right) = \sum^i \nu^i \frac{\partial}{\partial x^i} \Big|_p$$

and we can make $H_p TM$ & $V_p TM$ orthogonal by defining

$$\hat{g}(\xi, \eta) = g(\pi_*(\xi), \pi_*(\eta)) + g(\kappa(\xi), \kappa(\eta)).$$

In this metric the volume form μ_{SM} of SM is invariant under the geodesic flow: $\Phi_H: \mathbb{R} \times SM \rightarrow SM$ ∇

Q: What is the normal vector of ∂SM ?

A: $\partial SM = \{p \in SM \mid \pi(p) \in \partial M\}$

$$\Rightarrow T_p \partial SM = \left\{ \xi \in T_p SM \mid \pi_* \xi \in T_x \partial M \right\}$$

$$= \left\{ \xi \in T_p SM \mid g(\nu_x, \pi_* \xi) = 0 \right\}$$

Define $N_p := \nu_x^k \frac{\partial}{\partial x^k} \Big|_p$. Then $\hat{g}(N_p, N_p) = g(\nu_x, \nu_x) = 1$ and

$$\hat{g}(N_p, \xi) = g(\pi_*(N_p), \pi_*(\xi)) = g(\nu_x, \pi_* \xi) = 0 \quad \forall \xi \in T_p \partial SM,$$

so that N_p is the normal vector of $\partial SM \subset SM$ at p . \square

Santaló's formula

Let (M, g) be non-compact with C^∞ -boundary, and let $f \in L^1(SM)$. Then

$$\int_{SM} f(B) d\mu_B = \int_{\partial_- SM} \int_0^{\tau_+(z)} f(\bar{\sigma}_H^+(t, z)) dt g(z, H_z) dz.$$

Proof: Define $F: SM \rightarrow \mathbb{R} \times SM$; $F(B) = (\tau_-(B), \bar{\sigma}_H^{-\tau_-(B)}(B))$.

Then F is an injection with $\bar{\sigma}_H \circ F = \text{id}_{SM}$. Define

$$D = \{(t, z) \mid 0 < t < \tau_+(z), z \in \partial_- SM\}.$$

Then $F(SM) \setminus D$ and $SM \setminus \bar{\sigma}_H(D)$ are of measure zero, and

$$\int_{SM} f(B) d\mu_{SM} = \int_D f(\bar{\sigma}_H^+(t, z)) (\bar{\sigma}_H^+)^* d\mu_{SM}.$$

Let $\bar{X}_2, \dots, \bar{X}_{2n-1} \in T_z \partial_- SM$ be orthonormal. Then

$$H = \hat{g}(N_-, H_z) N_- + \sum_{k=2}^{2n-1} \hat{g}(\bar{X}_k, H_z) \bar{X}_k,$$

and the pull-back of the geodesic flow becomes

$$\begin{aligned} & ((\bar{\sigma}_H^+)^* \mu_{SM}|_{\bar{\sigma}_H^+(D)}) \left(\frac{\partial}{\partial t} \Big|_{(t, z)}, \bar{X}_2 \Big|_{(t, z)}, \dots, \bar{X}_{2n-1} \Big|_{(t, z)} \right) \\ &= \mu_{SM}|_{\bar{\sigma}_H^+(z)} \left(H \Big|_{\bar{\sigma}_H^+(z)}, (\bar{\sigma}_H^+)^* \bar{X}_2 \Big|_z, \dots, (\bar{\sigma}_H^+)^* \bar{X}_{2n-1} \Big|_z \right) \\ &= \mu_{SM}|_z \left(H_z, \bar{X}_2 \Big|_z, \dots, \bar{X}_{2n-1} \Big|_z \right) \\ &= \hat{g}(N_-, H_z) \underbrace{\mu_{SM}|_z(N_-, \bar{X}_2 \Big|_z, \dots, \bar{X}_{2n-1} \Big|_z)}_{=1} \\ &= g(z, \eta) \end{aligned}$$

$$\Rightarrow ((\bar{\sigma}_H^+)^* \mu_{SM}|_{\bar{\sigma}_H^+(D)}) = g(z, \eta) (dt \wedge \mu_{SM})|_{(t, z)} \quad \square$$